## Res. Asst. Muhammed Fatih ÇAKIR

#### **Personal Information**

Email: mfcakir@yildiz.edu.tr

Web: https://avesis.yildiz.edu.tr/mfcakir

Address: Yıldız Teknik Üniversitesi Makine Mühendisliği Bölümü 34349 Beşiktaş /İstanbul

#### International Researcher IDs

ORCID: 0000-0002-7459-5014

Publons / Web Of Science ResearcherID: AAA-5887-2022

ScopusID: 57219237693 Yoksis Researcher ID: 356955

#### **Education Information**

Doctorate, Yildiz Technical University, Faculty Of Mechanical Engineering, Department Of Mechanical Engineering, Turkey 2023 - Continues

Postgraduate, Yildiz Technical University, Faculty Of Mechanical Engineering, Department Of Mechanical Engineering, Turkey 2020 - 2023

Undergraduate, Yildiz Technical University, Faculty Of Mechanical Engineering, Department Of Mechanical Engineering, Turkey 2012 - 2020

### **Dissertations**

Postgraduate, Tekerlekli zırhlı aracın doğrusal matris eşitsizlikleri tabanlı H-sonsuz kontrolör ile aktif titreşim kontrolü, Yildiz Technical University, Faculty Of Mechanical Engineering, Department Of Mechanical Engineering, 2023

#### **Research Areas**

Mechanical Engineering, System Dynamics and Control, Modeling and Simulation of Dynamic Systems

## **Academic Titles / Tasks**

Research Assistant, Yildiz Technical University, Faculty Of Mechanical Engineering, Department Of Mechanical Engineering, 2021 - Continues

# Published journal articles indexed by SCI, SSCI, and AHCI

I. Modeling and Simulation of Elevation Dynamics of Main Battle Tank Weapon System with Linear Graph Method

ÇAKIR M. F., SEZER S., BAYRAKTAR M.

Arabian Journal for Science and Engineering, 2024 (SCI-Expanded)

II. Modelling of main battle tank and designing LQR controller to decrease weapon oscillations Ana muharebe tankinin modellenmesi ve silah salinimlarinin azaltilmasi için LQR kontrolör tasarim

Cakir M. F., BAYRAKTAR M.

Journal of the Faculty of Engineering and Architecture of Gazi University, vol.35, no.4, pp.1861-1876, 2020 (SCI-Expanded)

# Refereed Congress / Symposium Publications in Proceedings

I. Active Vibration Control of a Wheeled Armoured Vehicle with  $H\infty$  Controller Based on Linear Matrix Inequalities

Çakır M. F., Bayraktar M., Yazıcı H.

2nd Global Conference on Engineering Research - GLOBCER'22, Balıkesir, Turkey, 7 - 11 September 2022, pp.216-223

# **Metrics**

Publication: 3 Citation (WoS): 1 Citation (Scopus): 6 H-Index (WoS): 1 H-Index (Scopus): 1