

ELEKTROSTATİK

$\vec{E} = \frac{\rho_l}{2\pi\epsilon_0 r} \vec{a}_r, \vec{E} = \frac{\rho_s}{2\epsilon_0} \vec{a}_R$	$\vec{E} = Q\vec{E}, W = -\int \vec{F} \cdot d\vec{l}, W = -\int Q\vec{E} \cdot d\vec{l}$	$W_E = \frac{1}{2} \int \epsilon E^2 dv$
$I = \int \vec{J} \cdot d\vec{s}, \vec{J} = \sigma \vec{E}$	$\oint_s \vec{D} \cdot d\vec{s} = Q_{enc}, \vec{D} = \epsilon \vec{E}, \vec{F} = q\vec{E}$	$Q = \int_s \rho_s ds, Q = \int \rho_l d\vec{l}, Q = \int_v \rho_v dV [C]$
$\vec{D} = \frac{Q}{4\pi r^2} \vec{a}_r, \vec{D} = \frac{d\psi}{ds} \vec{a}$	$P(x, y, z), P(r, \phi, z), P(r, \theta, \phi)$	$\nabla \cdot \vec{D} = \rho, \text{div} \vec{E} = \frac{\rho}{\epsilon_0}, \vec{D} = \frac{d\psi}{ds}$
$\vec{F} = Q\vec{E}, \vec{F}_a = -Q\vec{E}$	$R = \frac{\ell}{\sigma A} (\Omega), R = \frac{V}{\int \vec{J} \cdot d\vec{s}} = \frac{V}{\int \sigma \vec{E} \cdot d\vec{s}}$	$W = \frac{1}{2} QV = \frac{1}{2} \left(\frac{\epsilon AV^2}{d} \right) = \frac{1}{2} CV^2$

$$d\vec{l} = dx\vec{a}_x + dy\vec{a}_y + dz\vec{a}_z \text{ (kartezyen)}$$

$$d\vec{l} = d\rho\vec{a}_\rho + \rho d\phi\vec{a}_\phi + dz\vec{a}_z \text{ (silindirik)}$$

$$d\vec{l} = dr\vec{a}_r + r d\theta\vec{a}_\theta + r \sin(\theta) d\phi\vec{a}_\phi \text{ (küresel)}$$

$$V_{AB} = \frac{W}{Q} = -\int_B^A \vec{E} \cdot d\vec{l}$$

$$V_{AB} = \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{r_A} - \frac{1}{r_B} \right)$$

$$\nabla V = \frac{\partial V}{\partial x} \vec{a}_x + \frac{\partial V}{\partial y} \vec{a}_y + \frac{\partial V}{\partial z} \vec{a}_z$$

$$\nabla V = \frac{\partial V}{\partial \rho} \vec{a}_\rho + \frac{1}{\rho} \frac{\partial V}{\partial \phi} \vec{a}_\phi + \frac{\partial V}{\partial z} \vec{a}_z$$

$$\vec{E} = -\nabla V, \oint \vec{D} \cdot d\vec{s} = \int (\nabla \cdot \vec{D}) dv$$

$$\mu_0 = 4\pi 10^{-7} \text{ H/m}, \epsilon_r = \frac{\epsilon}{\epsilon_0}$$

$$\epsilon_0 = 8,854 \cdot 10^{-12} \text{ F/m}, \mu_r = \frac{\mu}{\mu_0}$$

$$\nabla V = \frac{\partial V}{\partial r} \vec{a}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \vec{a}_\theta + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \vec{a}_\phi$$

	Kartezyen Koordinatlar (x, y, z) $-\infty < x, y, z < +\infty$	Silindirik Koordinatlar (ρ, ϕ, z) $0 \leq \rho < \infty; 0 \leq \phi < 2\pi; -\infty < z < \infty$	Küresel Koordinatlar (r, θ, ϕ) $0 \leq R < +\infty; 0 \leq \theta \leq \pi; 0 \leq \phi < 2\pi$
Diferansiyel Hacim, dV	$dx dy dz$	$\rho d\rho d\phi dz$	$r^2 \sin \theta d\theta d\phi dr$
Diferansiyel Alan, dS	$dy dz$ $dx dz$ $dx dy$	$\rho d\phi dz$ $d\rho dz$ $\rho d\rho d\phi$	$r^2 \sin \theta d\theta d\phi$ $r \sin \theta d\phi dr$ $r d\theta dr$
Diferansiyel Uzunluk, $d\ell$	dx dy dz	$d\rho$ $\rho d\phi$ dz	dr $r d\theta$ $r \sin \theta d\phi$

$C_1 = \frac{\epsilon_0 \epsilon_{r1} A_1}{d}, C_2 = \frac{\epsilon_0 \epsilon_{r2} A_2}{d}$ $C_{eq} = C_1 + C_2 = \frac{\epsilon_0}{d} (\epsilon_{r1} A_1 + \epsilon_{r2} A_2)$ $C_1 = \frac{\epsilon_0 \epsilon_{r1} A}{d_1}, C_2 = \frac{\epsilon_0 \epsilon_{r2} A}{d_2}$ $\frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_2} = \frac{\epsilon_{r2} d_1 + \epsilon_{r1} d_2}{\epsilon_0 \epsilon_{r1} \epsilon_{r2} A}$	$\vec{\nabla} \cdot \vec{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$ $\vec{\nabla} \cdot \vec{A} = \frac{1}{r} \frac{\partial (r A_r)}{\partial r} + \frac{1}{r} \frac{\partial A_\phi}{\partial \phi} + \frac{\partial A_z}{\partial z}$ $\vec{\nabla} \cdot \vec{A} = \frac{1}{r^2} \frac{\partial (r^2 A_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial (A_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial (A_\phi)}{\partial \phi}$ $W_E = \frac{1}{2} \int \rho V dV = \frac{1}{2} \int \vec{D} \cdot \vec{E} dV = \frac{1}{2} \int \epsilon \vec{E} \cdot \vec{E} dV = \frac{1}{2} \int \frac{D^2}{\epsilon} dV$
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$\vec{F} = \frac{Q_1 Q_2}{4\pi\epsilon_0 R^2} \vec{a}_R, \vec{E} = \frac{Q}{4\pi\epsilon_0 R^2} \vec{a}_R, V = \frac{Q}{4\pi\epsilon_0 R}$ $\vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{\rho_l d\ell}{R^2} \vec{a}_R, \vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{\rho_s ds}{R^2} \vec{a}_R, \vec{E} = \frac{1}{4\pi\epsilon_0} \int \frac{\rho_v dv}{R^2} \vec{a}_R$ $V = \frac{1}{4\pi\epsilon_0} \int \frac{\rho_l d\ell}{R}, V = \frac{1}{4\pi\epsilon_0} \int \frac{\rho_s ds}{R}, V = \frac{1}{4\pi\epsilon_0} \int \frac{\rho_v dv}{R}$	$\vec{D} = \epsilon_0 \vec{E} + \vec{P}, \vec{P} = \chi_e \epsilon_0 \vec{E}$ $\vec{D} = \epsilon_0 (1 + \chi_e) \vec{E} = \epsilon_0 \epsilon_r \vec{E}$ $C = Q/V = \epsilon_0 \epsilon_r A/d$
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$$\vec{A} \cdot \vec{B} = A_x B_x + A_y B_y + A_z B_z$$

$$\vec{A} \times \vec{B} = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ A_x & A_y & A_z \\ B_x & B_y & B_z \end{vmatrix}$$

MANYETİK

$$\vec{H} = \frac{\int \vec{I} d\vec{\ell} \times \vec{a}_R}{4\pi R^2} \quad L = \frac{N\phi}{I}$$

$$\vec{H} = \frac{I}{2\pi r} \vec{a}_\phi \quad [A/m] \quad \vec{I} = \int \vec{J} d\vec{s}$$

$$\oint \vec{H} \cdot d\vec{\ell} = I_{i\phi} \quad \vec{J} = \rho \vec{U} = \nabla \times \vec{E}$$

$$\nabla \times \vec{H} = \vec{J} \quad W = \frac{1}{2} CV^2$$

$$\vec{B} = \mu_0 \vec{H} \quad [T]$$

$$\phi = \int \vec{B} \cdot d\vec{s}$$

$$\nabla \times \vec{A} = \vec{B}$$

$$\vec{A} = \oint \frac{\mu \vec{I} d\vec{\ell}}{4\pi R}$$

$$\vec{F} = \rho \vec{U} \times \vec{B}$$

$$\vec{F} = \rho (\vec{E} + \vec{U} \times \vec{B})$$

$$\vec{F} = \int \vec{I} (d\vec{\ell} \times \vec{B})$$

$$L = \frac{N\phi}{I}$$

$$\vec{I} = \int \vec{J} d\vec{s}$$

$$\vec{J} = \rho \vec{U} = \nabla \times \vec{E}$$

$$\vec{B} = \frac{\mu_0 I}{2\pi r} \vec{a}_\phi, \quad \Phi = \int_s \vec{B} \cdot d\vec{s}, \quad \vec{F} = I \vec{L} \times \vec{B}, \quad \vec{B} = \nabla \times \vec{A}$$

$$H_a \ell_a = \frac{\phi}{\mu_0 S_a} \ell_a, \quad S_a = (a + \ell_a)(b + \ell_a), \quad \Phi = \int_s \vec{B} \cdot d\vec{s}, \quad \vec{A} = \frac{\mu}{4\pi} \int_l \frac{I d\vec{\ell}}{r}$$

$$\vec{B} = \frac{\mu_0 I}{4\pi r} \left[\frac{b}{\sqrt{\rho^2 + b^2}} - \frac{a}{\sqrt{\rho^2 + a^2}} \right] \vec{a}_\phi, \quad \vec{B} = \frac{\mu_0 I b^2}{2(b^2 + z^2)^{3/2}} \vec{a}_z$$

$$\nabla \times \vec{A} = \left(\frac{\partial A_z}{\partial y} - \frac{\partial A_y}{\partial z} \right) \vec{a}_x + \left(\frac{\partial A_x}{\partial z} - \frac{\partial A_z}{\partial x} \right) \vec{a}_y + \left(\frac{\partial A_y}{\partial x} - \frac{\partial A_x}{\partial y} \right) \vec{a}_z$$

$$\nabla \times \vec{A} = \left(\frac{1}{r} \frac{\partial A_z}{\partial \phi} - \frac{\partial A_\phi}{\partial z} \right) \vec{a}_r + \left(\frac{\partial A_r}{\partial z} - \frac{\partial A_z}{\partial r} \right) \vec{a}_\phi + \frac{1}{r} \left(\frac{\partial(r A_\phi)}{\partial r} - \frac{\partial A_r}{\partial \phi} \right) \vec{a}_z$$

$$\nabla \times \vec{A} = \frac{1}{r \sin \theta} \left(\frac{\partial(A_\phi \sin \theta)}{\partial \theta} - \frac{\partial A_\theta}{\partial \phi} \right) \vec{a}_r + \frac{1}{r} \left(\frac{1}{\sin \theta} \frac{\partial A_r}{\partial \phi} - \frac{\partial(r A_\phi)}{\partial r} \right) \vec{a}_\theta + \frac{1}{r} \left(\frac{\partial(r A_\theta)}{\partial r} - \frac{\partial A_r}{\partial \theta} \right) \vec{a}_\phi$$

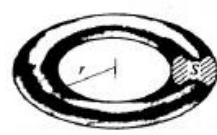
$$\oint \vec{H} \cdot d\vec{\ell} = I, \quad \nabla \times \vec{H} = \vec{J}, \quad \Phi = \oint \vec{A} \cdot d\vec{\ell},$$

$$\nabla \times \vec{B} = \begin{vmatrix} \vec{a}_x & \vec{a}_y & \vec{a}_z \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ B_x & B_y & B_z \end{vmatrix}$$



$$L = \frac{\mu_0 N^2 a}{2\pi} \ln \frac{r_2}{r_1} \quad (H)$$

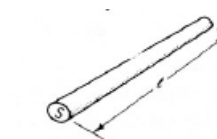
N sarımlı
Şekil 11-3 Toroid, kare kesitli



$$L = \frac{\mu_0 N^2 S}{2\pi r} \quad (H)$$

(ortalama r yarıçapında ortalama akı yoğunluğu varsayılmıştır)

Şekil 11-4 Toroid, genel S kesitli



$$L = \frac{\mu_0 N^2 S}{l} \quad (H)$$

Şekil 11-7 Küçük S kesit alanlı uzun solenoid

$$i_D = \int_S \vec{J}_D \cdot d\vec{S} = \int_S \frac{\partial \vec{D}}{\partial t} \cdot d\vec{S} = \frac{d}{dt} \int_S \vec{D} \cdot d\vec{S}$$

$$\vec{J}_t = \vec{J}_c + \vec{J}_D = \sigma \vec{E}$$

$$v_{ab} = \int_b^a \vec{E}_m \cdot d\vec{l} = \int_b^a (\vec{U} \times \vec{B}) \cdot d\vec{l}$$

$$\oint_C \vec{E} \cdot d\vec{l} = -\frac{d}{dt} \int_S \vec{B} \cdot d\vec{S}$$

$$\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t}$$

$$\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\nabla \cdot \vec{D} = 0$$

$$\nabla \cdot \vec{B} = 0$$

$$\oint \vec{H} \cdot d\vec{l} = \int_S \left(\frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{S}$$

$$\oint \vec{E} \cdot d\vec{l} = \int_S \left(-\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{S}$$

$$\oint_S \vec{D} \cdot d\vec{S} = 0$$

$$\oint_S \vec{B} \cdot d\vec{S} = 0$$