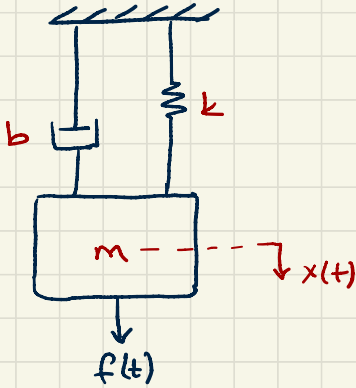


(6M13181)
OTOMATİK KONTROL

6. HAFTA

10.11.2023

MEKANİK SİSTEMLERİN BLOK DİTİGRAMLAR İLE İFADESİ



$$T(s) = \frac{X(s)}{F(s)} = ? \quad \begin{array}{l} \text{Çıkış} \checkmark \\ \text{Giriş} \checkmark \end{array}$$

Transfer fonksiyonunu sistemin blok diyagramını oluşturarak bulalım. Başlangıç koşulları sıfır ve sistem dengededir.

$$\sum F(t) = m \cdot a$$

$$\begin{aligned} f(t) &= m \cdot \ddot{x}(t) \\ \Rightarrow f(s) &= m s^2 X(s) \end{aligned}$$

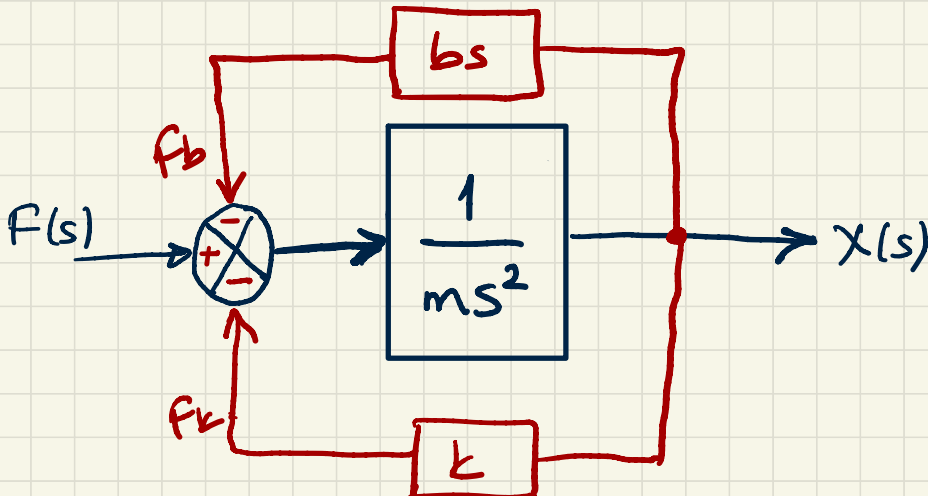
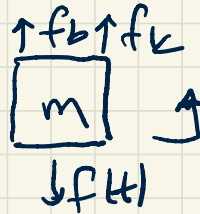
$$X(s) = \frac{F(s)}{m s^2}$$

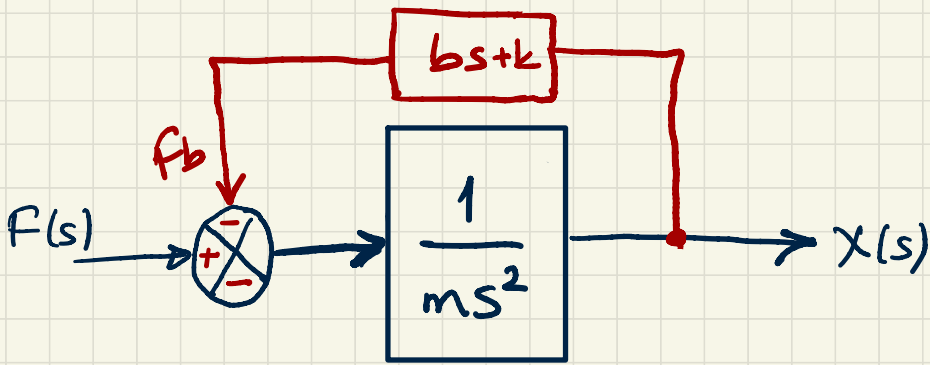
$$f_b = b \dot{x}(t)$$

$$F_b(s) = b s X(s)$$

$$f_k = k \cdot x(t)$$

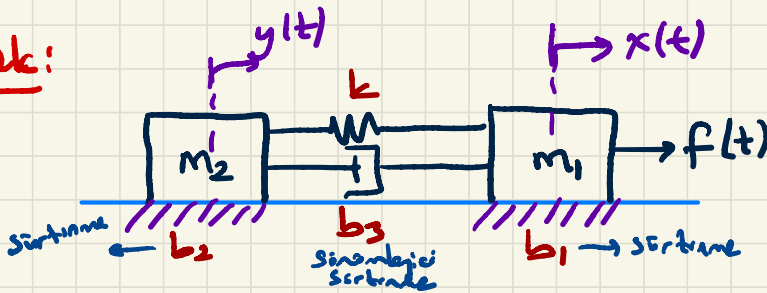
$$F_k(s) = k X(s)$$





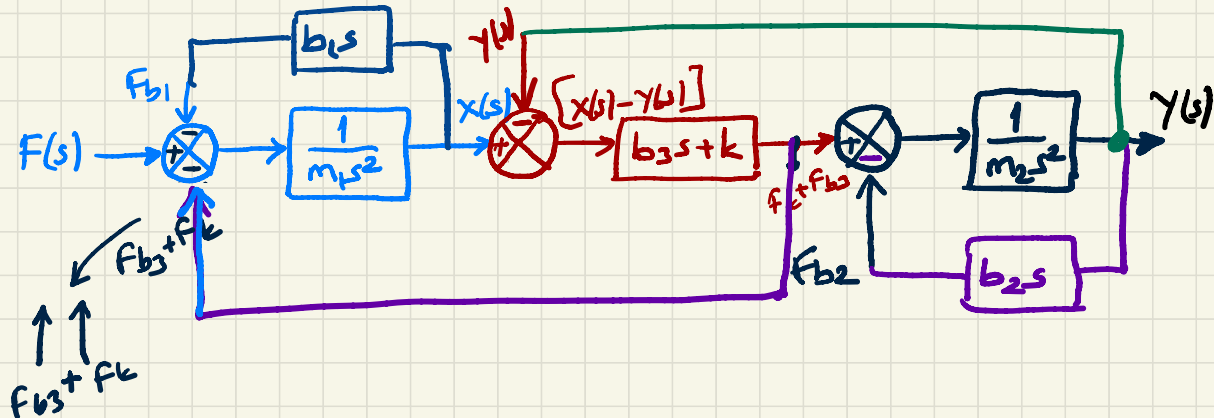
$$\frac{X(s)}{F(s)} = \frac{1/ms^2}{1 + \frac{(bs+k)}{ms^2}} = \frac{1}{ms^2} \cdot \frac{ms^2}{ms^2 + bs + k} = \frac{1}{ms^2 + bs + k}$$

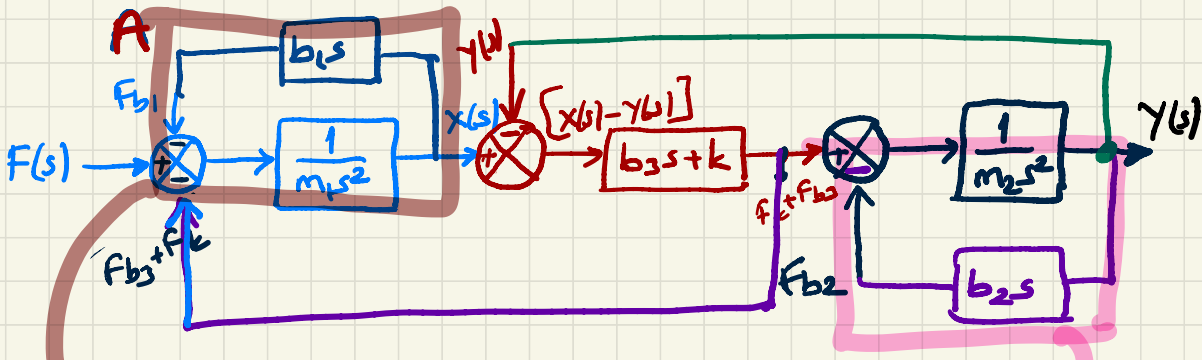
Örnek:



$$T(s) = \frac{Y(s)}{F(s)}$$

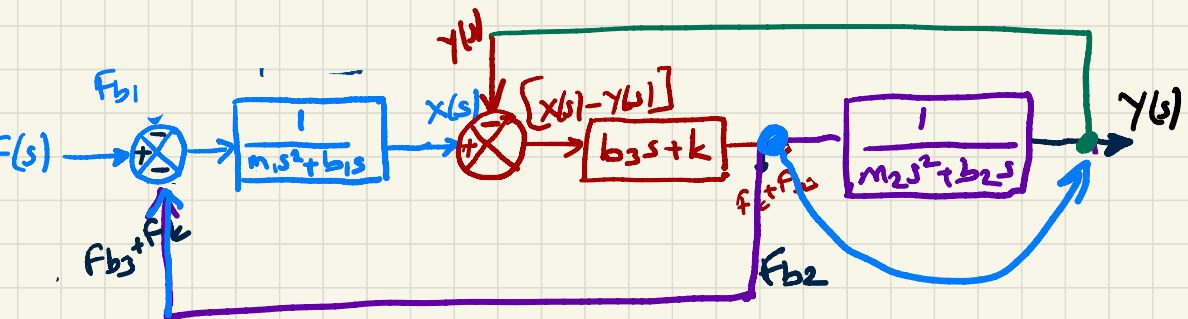
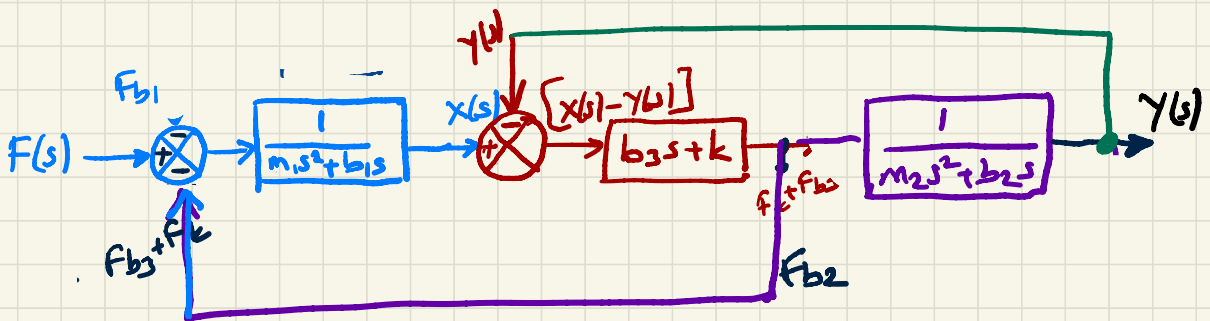
$$f_{b1} = b_1 \dot{x}(t), \quad f_{b3} = b_3 (\dot{x}(t) - \dot{y}(t)), \quad f_k = k(x(t) - y(t)), \quad f_{b2} = b_2 \dot{y}(t)$$

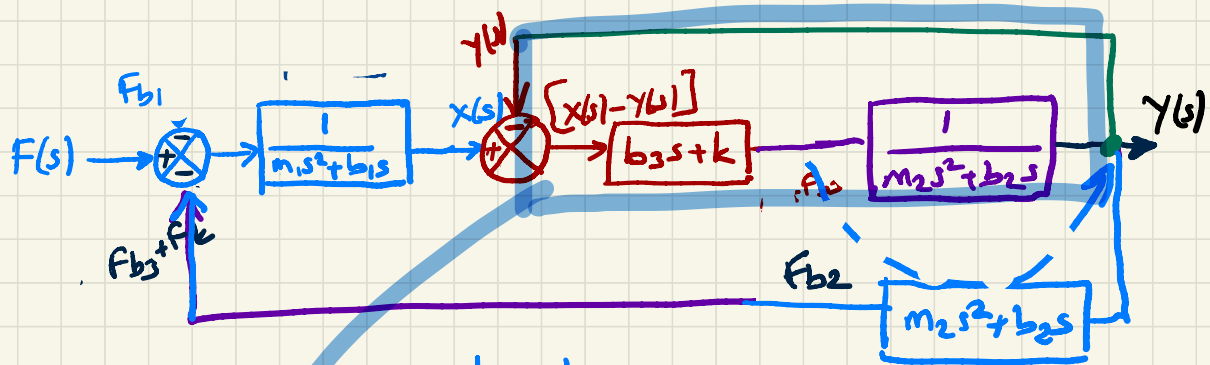




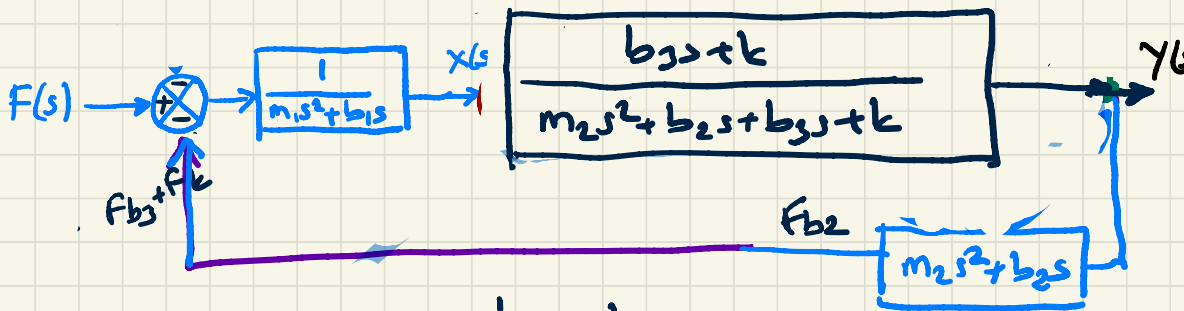
$$A = \frac{\frac{1}{m_1 s^2}}{1 + (b_1 s) \frac{1}{m_1 s^2}} = \frac{1}{m_1 s^2 + b_1 s}$$

$$B = \frac{\frac{1}{m_2 s^2} B}{1 + b_2 s \cdot \frac{1}{m_2 s^2}} = \frac{1}{m_2 s^2 + b_2 s}$$





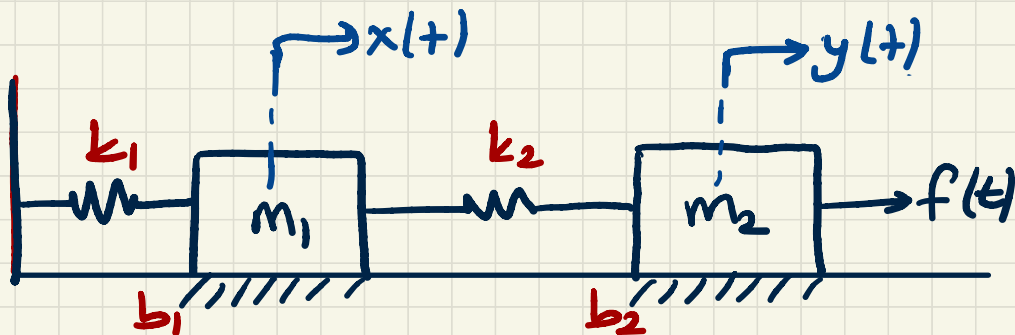
$$C = \frac{\frac{b_3s+k}{m_2s^2+b_2s}}{1 + (1) \left(\frac{b_3s+k}{m_2s^2+b_2s} \right)} = \frac{b_3s+k}{m_2s^2+b_2s+b_3s+k}$$



$$\frac{Y(s)}{F(s)} = \frac{\frac{1}{m_1s^2+b_1s} \cdot \frac{b_3s+k}{m_2s^2+b_2s+b_3s+k}}{1 + (m_2s^2+b_2s) \left(\frac{1}{m_1s^2+b_1s} \cdot \frac{b_3s+k}{m_2s^2+b_2s+b_3s+k} \right)}$$

$$\frac{Y(s)}{F(s)} = \frac{b_3s+k}{(m_1s^2+b_1s)(m_2s^2+b_2s+b_3s+k) + (b_3s+k)(m_2s^2+b_2s)}$$

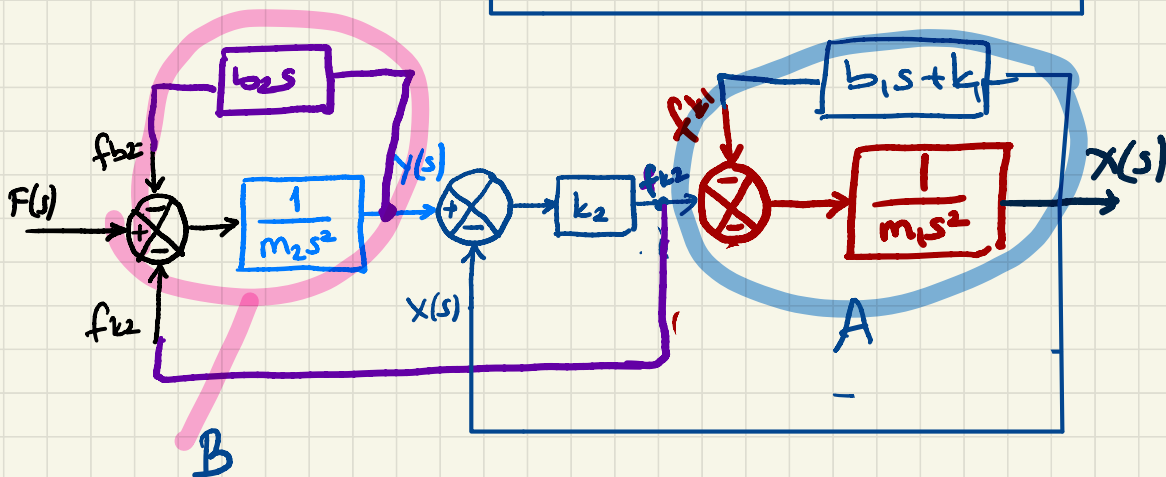
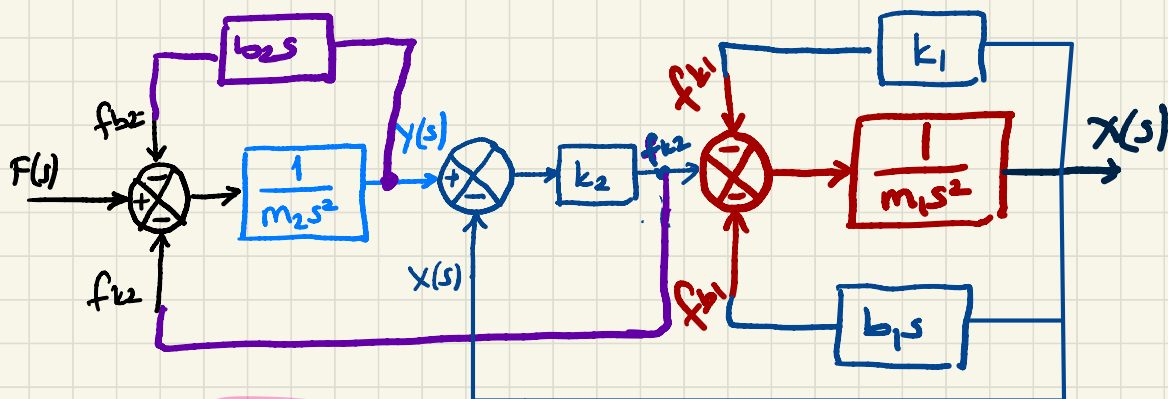
Örnek:

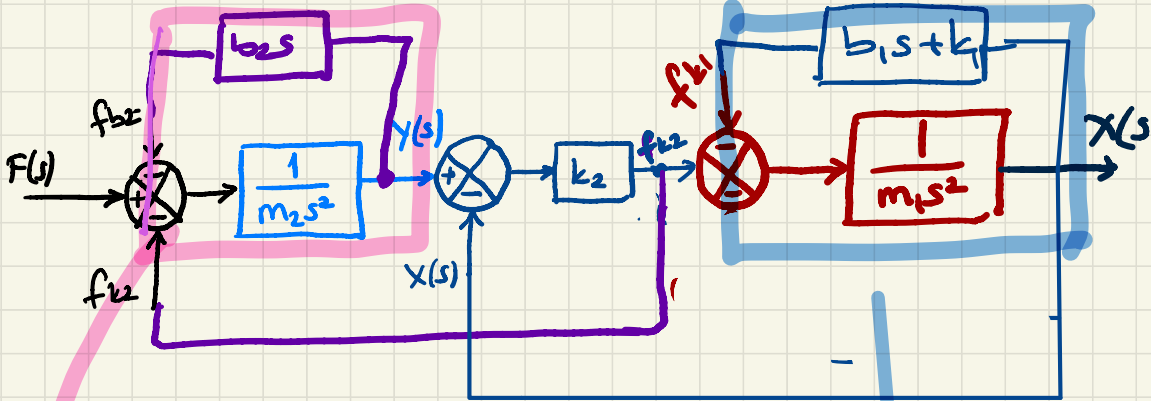


$$T(s) = \frac{X(s)}{F(s)} = ?$$

$$f_{b_2} = b_2 \dot{y}(t), f_{b_1} = b_1 \dot{x}(t)$$

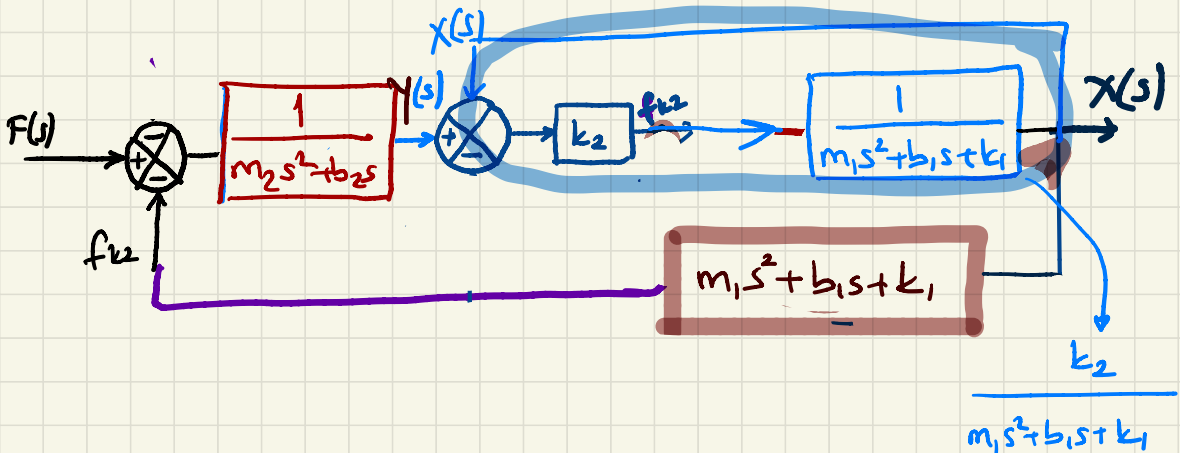
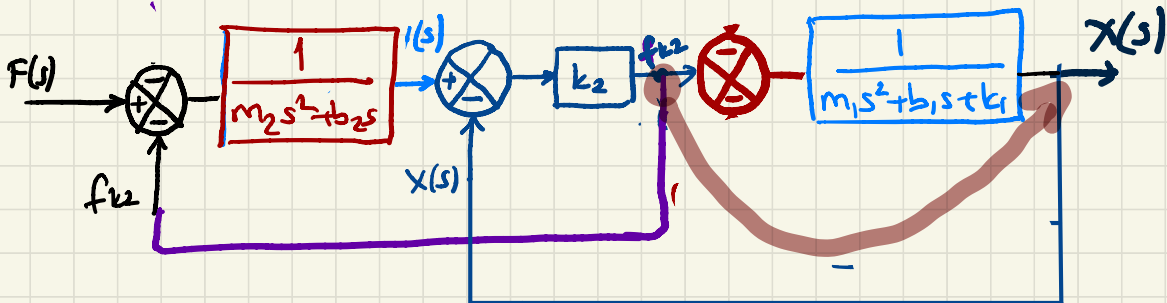
$$f_{k_2} = k_2(y - x), f_{k_1} = k_1 x$$

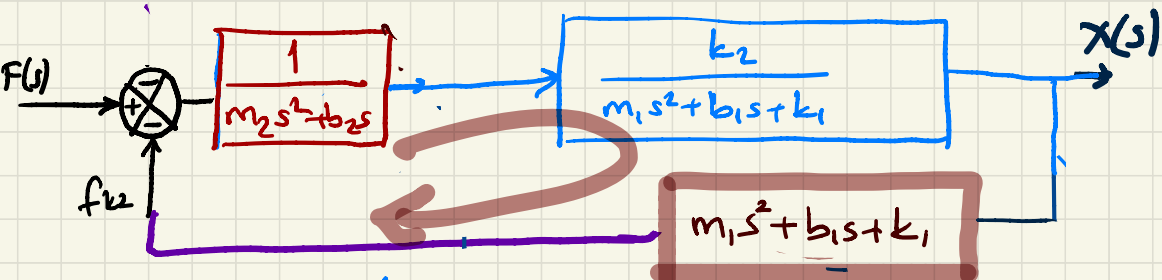




$$B = \frac{\frac{1}{m_2 s^2}}{1 + \frac{b_2 s}{m_2 s^2}} = \frac{1}{m_2 s^2 + b_2 s}$$

$$A = \frac{\frac{1}{m_1 s^2}}{1 + \frac{b_1 s + k_1}{m_1 s^2}} = \frac{1}{m_1 s^2 + b_1 s + k_1}$$

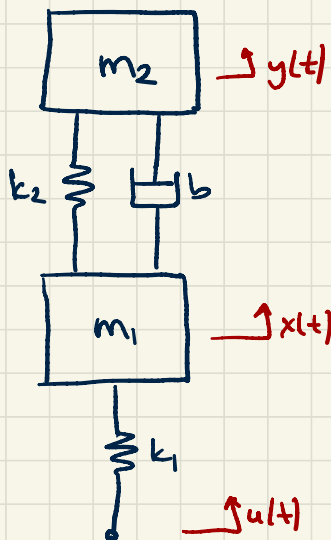




$$\frac{X(s)}{F(s)} = \frac{\left(\frac{1}{m_2 s^2 + b_2 s} \right) \left(\frac{k_2}{m_1 s^2 + b_1 s + k_1} \right)}{1 + \left(\frac{1}{m_2 s^2 + b_2 s} \right) \left(\frac{k_2}{m_1 s^2 + b_1 s + k_1} \right) (m_1 s^2 + b_1 s + k_1)}$$

$$\frac{X(s)}{F(s)} = \frac{k_2}{(m_2 s^2 + b_2 s) (m_1 s^2 + b_1 s + k_1 + k_2) + k_2 (m_1 s^2 + b_1 s + k_1)}$$

10r:

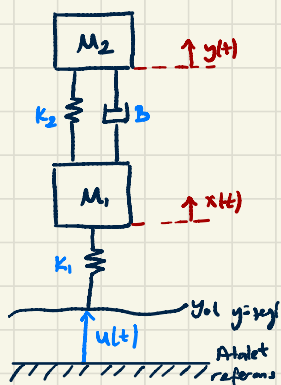


$$T(s) = \frac{Y(s)}{U(s)} = ?$$

$$f_{k1} = k_1(u - x)$$

$$f_{k2} = k_2(x - y)$$

$$f_b = b(\dot{x} - \dot{y})$$



(3. Hafta FBD)

