

Differentiation Under the Integral Sign

If the integrand is a function of one or more parameters in addition to the variable of integration, then the integral between the limits which may be constants or functions of the parameters is a function of these parameters.

Ex:

$$i) \int_0^{1/2} \sin \alpha x \, dx = \left. -\frac{1}{\alpha} \cos \alpha x \right|_0^{1/2} = \frac{1}{\alpha} - \frac{1}{\alpha} \cos \alpha \frac{1}{2} = f(\alpha)$$

$$ii) \int_1^2 (x+\alpha)^2 \, dx = \left. \frac{(x+\alpha)^3}{3} \right|_1^2 = \frac{(2+\alpha)^3 - (1+\alpha)^3}{3} = G(\alpha)$$

Thus, in integral,

$$\int_a^b f(x, \alpha) \, dx = F(\alpha)$$

$$\int_a^b f(x, \alpha, \beta) \, dx = F(\alpha, \beta)$$

where a, b may be constants or functions of parameters.

Sometimes, $f(x, \alpha)$ is such that the evaluation of the integral is very complicated or impossible. However, the integral with integrand $\frac{\partial f}{\partial \alpha}$ may be easily evaluated.

Leibnitz's Rule for Differentiation Under the Integral Sign

Theorem: If $f(x, \alpha)$ and $\frac{\partial f(x, \alpha)}{\partial \alpha}$ are continuous functions of x and α for $a \leq x \leq b$,

$c \leq \alpha \leq d$, a, b being independent of α , then,

$$\frac{d}{d\alpha} \int_a^b f(x, \alpha) \, dx = \int_a^b \frac{\partial f(x, \alpha)}{\partial \alpha} \, dx$$

Proof:

$$\text{Let } F(\alpha) = \int_a^b f(x, \alpha) \, dx \quad (*)$$

Let α changes $\alpha + \Delta \alpha$ ($[\alpha, \alpha + \Delta \alpha]$ in $[c, d]$)

$$F(\alpha + \Delta\alpha) = \int_a^b f(x, \alpha + \Delta\alpha) dx \quad (**)$$

$$(**) - (*) : F(\alpha + \Delta\alpha) - F(\alpha)$$

$$= \int_a^b (f(x, \alpha + \Delta\alpha) - f(x, \alpha)) dx \quad (***)$$

By Lagrange's Mean Value Theorem (or the Mean Value Theorem):

$$f(x, \alpha + \Delta\alpha) - f(x, \alpha) = \Delta\alpha \cdot \frac{\partial f}{\partial \alpha}(x, \alpha + \theta\Delta\alpha) \quad \text{where } 0 < \theta < 1$$

$$F(\alpha + \Delta\alpha) - F(\alpha) = \int_a^b \Delta\alpha \cdot \frac{\partial f}{\partial \alpha}(x, \alpha + \theta\Delta\alpha) dx, \quad 0 < \theta < 1$$

$$\frac{F(\alpha + \Delta\alpha) - F(\alpha)}{\Delta\alpha} = \int_a^b \frac{\partial f}{\partial \alpha}(x, \alpha + \theta\Delta\alpha) dx$$

Taking limits as $\Delta\alpha \rightarrow 0$, we take,

$$\lim_{\Delta\alpha \rightarrow 0} \frac{F(\alpha + \Delta\alpha) - F(\alpha)}{\Delta\alpha} = \lim_{\Delta\alpha \rightarrow 0} \int_a^b \frac{\partial f}{\partial \alpha}(x, \alpha + \theta\Delta\alpha) dx$$

$$F'(\alpha) = \frac{d(F(\alpha))}{d\alpha}$$

$$\frac{d}{d\alpha} \int_a^b f(x, \alpha) dx = \int_a^b \frac{\partial f}{\partial \alpha}(x, \alpha) dx$$

Note 1: Thus, Leibnitz's Rule states that,

$$F(\alpha) = \int_a^b f(x, \alpha) dx \Rightarrow F'(\alpha) = \int_a^b \frac{\partial f}{\partial \alpha}(x, \alpha) dx$$

Similarly;

$$F(\alpha, \beta) = \int_a^b f(x, \alpha, \beta) dx \Rightarrow \frac{\partial F(\alpha, \beta)}{\partial \alpha} = \int_a^b \frac{\partial f}{\partial \alpha}(x, \alpha, \beta) dx; \quad \frac{\partial F(\alpha, \beta)}{\partial \beta} = \int_a^b \frac{\partial f}{\partial \beta}(x, \alpha, \beta) dx$$

Note 2: From definite integrals, if a function f is,

i) Continuous on $[a, b]$ then $\exists$ a some number c in (a, b) such that,

$$\int_a^b f(x) dx = (b-a)f(c).$$

ii) Continuous on $[a, a+h]$ then $\exists$ a real number θ in $(0, 1)$ such that,

$$\int_a^{a+h} f(x) dx = h f(a+\theta h).$$

Theorem: If $f(x, \alpha)$ and $\frac{\partial f}{\partial x}(x, \alpha)$ are continuous functions of x and α and for

$a \leq x \leq b$, $c \leq \alpha \leq d$ and a, b are themselves functions of parameter α , possessing continuous first order derivatives, then,

$$\left\{ \frac{d}{d\alpha} \int_a^b f(x, \alpha) dx = \int_a^b \frac{\partial f}{\partial \alpha}(x, \alpha) dx + \frac{db}{d\alpha} f(b, \alpha) - \frac{da}{d\alpha} f(a, \alpha) \right\} \begin{cases} a = a(\alpha) \\ b = b(\alpha) \end{cases}$$

Proof:

$$\text{Let } F(\alpha) = \int_a^b f(x, \alpha) dx \quad (*)$$

$$F(\alpha + \Delta\alpha) = \int_{a+\Delta a}^{b+\Delta b} f(x, \alpha + \Delta\alpha) dx \quad (**)$$

$$\begin{cases} \alpha \rightarrow \alpha + \Delta\alpha \\ a \rightarrow a + \Delta a \\ b \rightarrow b + \Delta b \end{cases}$$

$$(**) - (*) : F(\alpha + \Delta\alpha) - F(\alpha)$$

$$= \int_{a+\Delta a}^{b+\Delta b} f(x, \alpha + \Delta\alpha) dx - \int_a^b f(x, \alpha) dx + \int_{a+\Delta a}^{b+\Delta b} f(x, \alpha) dx - \int_{a+\Delta a}^b f(x, \alpha) dx$$

$$= \int_{a+\Delta a}^{b+\Delta b} (f(x, \alpha + \Delta\alpha) - f(x, \alpha)) dx + \int_{a+\Delta a}^{b+\Delta b} f(x, \alpha) dx - \int_{a+\Delta a}^b f(x, \alpha) dx$$

$$\left\{ \int_{a+\Delta a}^{b+\Delta b} f(x, \alpha) dx = \int_{a+\Delta a}^b f(x, \alpha) dx + \int_b^{b+\Delta b} f(x, \alpha) dx = - \int_b^{a+\Delta a} f(x, \alpha) dx + \int_b^{b+\Delta b} f(x, \alpha) dx \right\}$$

$$= \int_{a+\Delta a}^{b+\Delta b} \Delta x \cdot \frac{\partial f}{\partial x}(x, \alpha + \theta \Delta x) dx + \int_b^{b+\Delta b} f(x, \alpha) dx - \underbrace{\left(\int_a^b f(x, \alpha) dx + \int_b^{a+\Delta a} f(x, \alpha) dx \right)}_{\int_a^{a+\Delta a} f(x, \alpha) dx}$$

$$F(x+\Delta x) - F(x) = \int_{a+\Delta a}^{b+\Delta b} \Delta x \cdot \frac{\partial f}{\partial x}(x, \alpha + \theta \Delta x) dx + \Delta b \cdot f(b + \theta_1 \Delta b, \alpha) - \Delta a \cdot f(a + \theta_2 \Delta a, \alpha)$$

$$\frac{F(x+\Delta x) - F(x)}{\Delta x} = \int_{a+\Delta a}^{b+\Delta b} \frac{\partial f}{\partial x}(x, \alpha + \theta \Delta x) dx + \frac{\Delta b}{\Delta x} f(b + \theta_1 \Delta b, \alpha) - \frac{\Delta a}{\Delta x} f(a + \theta_2 \Delta a, \alpha)$$

where $0 < \theta, \theta_1, \theta_2 < 1$,

Taking limit as $\Delta x, \Delta a, \Delta b \rightarrow 0$,

$$\lim_{\Delta x \rightarrow 0} \frac{F(x+\Delta x) - F(x)}{\Delta x} = \lim_{\Delta x \rightarrow 0} \int_{a+\Delta a}^{b+\Delta b} \frac{\partial f}{\partial x}(x, \alpha + \theta \Delta x) dx + \lim_{\Delta x \rightarrow 0} \frac{\Delta b}{\Delta x} \cdot \lim_{\Delta b \rightarrow 0} f(b + \theta_1 \Delta b, \alpha)$$

$$- \lim_{\Delta x \rightarrow 0} \frac{\Delta a}{\Delta x} \cdot \lim_{\Delta a \rightarrow 0} f(a + \theta_2 \Delta a, \alpha)$$

$\downarrow$
 $\frac{d(F(x))}{dx}$
 $F'(x)$

$\downarrow$
 $f(a, \alpha)$

$\downarrow$
 $f(b, \alpha)$

$$\Rightarrow \frac{d}{dx} \int_a^b f(x, \alpha) dx = \int_a^b \frac{\partial f}{\partial x}(x, \alpha) dx + \frac{db}{dx} f(b, \alpha) - \frac{da}{dx} f(a, \alpha) \quad \checkmark$$

Ex: 1) $\frac{d}{dx} \int_{\pi/4}^x \sin t \cdot dt = ?$

2) $I = \int_{x^2}^{\sin^{-1}x} \frac{\sin t}{t} dt$ then $\frac{dI}{dx} = ?$

3) Find, $\int_0^{\infty} t^n \cdot e^{-Kt^2} dt$ ($K > 0$) for odd n .

4) If, $\phi(x) = \int_{\alpha}^{\alpha^2} \frac{\sin x \cdot x}{x} dx$ find $\phi'(\alpha)$ where $\alpha \neq 0$.

5) Find, $I(x) = \int_0^1 \ln(x^2 + y^2) dy$.

Solution:

1) $\frac{d}{dx} \int_{\pi/4}^x \sin t \cdot dt = \frac{d}{dx} \left(-\cos t \Big|_{\pi/4}^x \right) = \frac{d}{dx} \left(-\cos x + \cos \pi/4 \right) = \sin x$.

2nd method by using Leibnitz's Rule;

$$\begin{cases} a = x \\ b = x \\ a = \pi/4 \end{cases}$$

$$\frac{d}{dx} \int_{\pi/4}^x \sin t dt = \underbrace{\int_{\pi/4}^x \frac{d}{dx} \sin t dt}_0 + \underbrace{\frac{d(x)}{dx} \sin x}_1 - \underbrace{\frac{d(\pi/4)}{dx} \cdot \sin \pi/4}_0$$

$$= \sin x$$

$$\begin{aligned}
 2) \quad \frac{d\hat{I}}{dx} &= \frac{d}{dx} \int_{x^2}^{\sin^{-1}x} \frac{\sin t}{t} dt = \int_{x^2}^{\sin^{-1}x} \underbrace{\frac{d}{dx} \left(\frac{\sin t}{t} \right)}_0 dt + \frac{d(\sin^{-1}x)}{dx} \cdot \frac{\sin(\sin^{-1}x)}{\sin^{-1}x} - \frac{d(x^2)}{dx} \cdot \frac{\sin(x^2)}{x^2} \\
 &= \frac{1}{\sqrt{1-x^2}} \cdot \frac{x}{\sin^{-1}x} - 2x \cdot \frac{\sin(x^2)}{x^2}
 \end{aligned}$$

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$$3) \quad \int_0^{\infty} t^n e^{-Kt^2} dt = F(K) \quad \left\{ \begin{array}{l} \text{integration variable} \\ \text{if } dt \text{ then parameter is } K \end{array} \right\}$$

$$\begin{aligned}
 n=1 \Rightarrow \int_0^{\infty} t e^{-Kt^2} dt &= \int_0^{\infty} e^u \cdot \frac{du}{-2K} = -\frac{1}{2K} e^u \bigg|_{t=0}^{\infty} \\
 &\quad \left\{ \begin{array}{l} -Kt^2 = u \\ -2Kt dt = du \end{array} \right\}
 \end{aligned}$$

$$\Rightarrow \hat{I} = -\frac{1}{2K} e^{-Kt^2} \bigg|_0^{\infty} = \frac{1}{2K} \checkmark$$

$$\int_0^{\infty} t e^{-Kt^2} dt = \frac{1}{2K} \quad \left\{ \text{Differentiate wrt } K \text{ both sides} \right\}$$

$$\Rightarrow \frac{d}{dK} \left(\int_0^{\infty} t e^{-Kt^2} dt \right) = \frac{d}{dK} \left(\frac{1}{2K} \right) \Rightarrow \int_0^{\infty} \frac{d}{dK} (t e^{-Kt^2}) dt = \frac{d}{dK} \left(\frac{1}{2K} \right)$$

$$\Rightarrow - \int_0^{\infty} t^2 e^{-Kt^2} dt = -\frac{1}{2K^2}$$

$$\Rightarrow \int_0^{\infty} t^2 e^{-Kt^2} dt = \frac{1}{2K^2} \checkmark$$

$$\int_0^{\infty} t^3 e^{-Kt^2} dt = \frac{1}{2K^2} \quad \left\{ \text{Diff. wrt } K \right\}$$

$$\Rightarrow \frac{d}{dK} \left(\int_0^{\infty} t^3 e^{-Kt^2} dt \right) = \frac{d}{dK} \left(\frac{1}{2K^2} \right) \Rightarrow - \int_0^{\infty} t^5 e^{-Kt^2} dt = -\frac{1}{K^3}$$

$$\Rightarrow \int_0^{\infty} t^5 e^{-Kt^2} dt = \frac{1}{K^3} \checkmark$$

$$\int_0^{\infty} t^5 e^{-Kt^2} dt = \frac{1}{K^3} \quad \left\{ \text{Diff. wrt } K \right\}$$

$$\Rightarrow \frac{d}{dK} \left(\int_0^{\infty} t^5 e^{-Kt^2} dt \right) = \frac{d}{dK} \left(\frac{1}{K^3} \right) \Rightarrow - \int_0^{\infty} t^7 e^{-Kt^2} dt = -\frac{3}{K^4}$$

$$\Rightarrow \int_0^{\infty} t^7 e^{-Kt^2} dt = \frac{3}{K^4} \checkmark$$

$$\vdots$$

$$\int_0^{\infty} t^{2n+1} e^{-Kt^2} dt = \frac{n!}{2 K^{n+1}} \quad \text{for } n=0,1,2,\dots$$

$$5) \int_0^1 \ln(x^2+y^2) dy = I(x)$$

$$\frac{dI}{dx} = \frac{d}{dx} \int_0^1 \ln(x^2+y^2) dy = \int_0^1 \frac{d}{dx} (\ln(x^2+y^2)) dy = \int_0^1 \frac{2x}{x^2+y^2} dy$$

$$\Rightarrow \frac{2x}{x^2} \int_0^1 \frac{dy}{1+(y/x)^2} \quad \left\{ \begin{array}{l} y=ux \Rightarrow y=xu \\ dy=xdu \end{array} \right\}$$

$$= \frac{2x}{x^2} \int_0^1 \frac{dy}{1+(y/x)^2} = \frac{2x}{x^2} \int \frac{x du}{1+u^2} = 2 \int \frac{du}{1+u^2}$$

$$= 2 \operatorname{Arctan} u \quad \checkmark$$

$$\Rightarrow 2 \operatorname{Arctan}(y/x) \Big|_{y=0}^1 = 2 \operatorname{Arctan}(1/x) - 2 \operatorname{Arctan}(0)$$

$$= 2 \operatorname{Arctan}(1/x) \quad \checkmark$$

$$\Rightarrow \frac{dI}{dx} = 2 \operatorname{Arctan}\left(\frac{1}{x}\right) \quad \left\{ \text{Integrate wrt } x \right\}$$

$$I(x) = 2 \int \operatorname{Arctan}\left(\frac{1}{x}\right) dx + C$$

$$\left\{ \begin{array}{l} u = \operatorname{Arctan}(1/x) \\ du = \frac{-1/x^2}{1+1/x^2} dx = \frac{-dx}{1+x^2} \\ dx = dv \\ x = v \end{array} \right\}$$

$$\Rightarrow I(x) = 2 \left(x \cdot \operatorname{Arctan}\left(\frac{1}{x}\right) + \int \frac{x dx}{1+x^2} \right) + C$$

$$= 2x \operatorname{Arctan}(1/x) + \ln(1+x^2) + C \quad \checkmark$$

for $x=0$,

$$\Rightarrow I(0) = \int_0^1 \ln(y^2) dy = 2 \int_0^1 \ln y dy$$

$$= 2 \lim_{a \rightarrow 0} \int_a^1 \ln y dy = 2 \lim_{a \rightarrow 0} (-a \ln a - 1)$$

$$= \underbrace{-2 \lim_{a \rightarrow 0} a \ln a}_{0} - 2 = -2 \quad \checkmark$$

$$\left. \vphantom{\lim_{a \rightarrow 0} a \ln a} \right\} C = -2$$

$$I(0) = \underbrace{2 \cdot 0 \cdot \operatorname{Arctan}(1/0)}_0 + \underbrace{\ln(1)}_0 + C = C$$

$$\Rightarrow I(x) = 2x \operatorname{Arctan}\left(\frac{1}{x}\right) + \ln(1+x^2) - 2.$$

HW: Evaluate the integral,

$$I = \int_0^{\infty} t^n e^{-at^2} dt \text{ for } n=2,4,\dots,2m \text{ if } \int_0^{\infty} e^{-at^2} dt = \frac{1}{2} \sqrt{\pi/a}.$$

Ex:

Show that $y = \int_0^x f(u) \sin(x-u) du$ satisfies $y'' + y = f(x)$.

$$y' = \frac{dy}{dx} = \frac{d}{dx} \int_0^x f(u) \sin(x-u) du = \int_0^x \frac{\partial}{\partial x} (f(u) \sin(x-u)) du + \underbrace{\frac{d(x)}{dx} f(x) \sin 0}_0 - \underbrace{\frac{d(0)}{dx} f(0) \sin x}_0$$

$$= \int_0^x \frac{\partial}{\partial x} (f(u) \sin(x-u)) du$$

$$= \int_0^x f(u) \cos(x-u) du \checkmark$$

$$y'' = \frac{dy'}{dx} = \frac{d}{dx} \left(\int_0^x f(u) \cos(x-u) du \right) = \int_0^x \frac{\partial}{\partial x} (f(u) \cos(x-u)) du + \underbrace{\frac{d(x)}{dx} f(x) \cos 0}_{f(x)} - \underbrace{\frac{d(0)}{dx} f(0) \cos x}_0$$

$$= \int_0^x \frac{\partial}{\partial x} (f(u) \cos(x-u)) du + f(x)$$

$$= - \int_0^x f(u) \sin(x-u) du + f(x) \checkmark$$

$$\Rightarrow y'' = - \int_0^x f(u) \sin(x-u) du + f(x)$$

$$y = \int_0^x f(u) \sin(x-u) du$$

$$y'' + y = f(x).$$

Gamma Function

Definition: If $n > 0$ then the integral,

$$\int_0^{\infty} x^{n-1} \cdot e^{-x} \cdot dx$$

which is obviously a function of n is called a Gamma Function and is denoted by $\Gamma(n)$. Thus,

$$\Gamma(n) = \int_0^{\infty} x^{n-1} \cdot e^{-x} \cdot dx, \quad \forall n > 0.$$

Gamma Function is also called the second Eulerian Integral. For example,

$$i) \int_0^{\infty} x^3 \cdot e^{-x} \cdot dx = \Gamma(4) \quad \left\{ n-1=3 \right\}$$

$$ii) \int_0^{\infty} x^{2/3} \cdot e^{-x} \cdot dx = \Gamma(5/3) \quad \left\{ n-1=\frac{2}{3} \right\}$$

Convergence of Gamma Function

Theorem:

$$\underbrace{\int_0^{\infty} x^{n-1} \cdot e^{-x} \cdot dx}_{\text{Converges}} \quad \text{iff } n > 0.$$

Proof: If $n \geq 1$, then integrand $x^{n-1} \cdot e^{-x}$ is continuous at $x=0$.

If $n < 1$, then integrand $\frac{e^{-x}}{x^{1-n}}$ has infinite discontinuity at $x=0$.

Thus, we have to examine the convergence at $x=0$ and $x=\infty$ both consider any positive number say 1, and examine the convergence of,

$$\int_0^{\infty} x^{n-1} \cdot e^{-x} \cdot dx = \underbrace{\int_0^1 x^{n-1} \cdot e^{-x} \cdot dx}_{\text{Converges at } x=0} + \underbrace{\int_1^{\infty} x^{n-1} \cdot e^{-x} \cdot dx}_{\text{Converges at } x=\infty} \quad \left. \vphantom{\int_0^{\infty}} \right\} \text{iff } n > 0.$$

Convergence at $x=0$ when $n < 1$

Let $f(x) = \frac{e^{-x}}{x^{1-n}}$, take $g(x) = \frac{1}{x^{1-n}}$, then,

$$\lim_{x \rightarrow 0^+} \frac{f(x)}{g(x)} = \lim_{x \rightarrow 0^+} e^{-x} = 1.$$

which is nonzero and finite. Also,

$$\int_0^1 g(x) dx = \int_0^1 \frac{dx}{x^{1-n}} \text{ is convergent } \{ 1-n < 1, n > 0 \}$$

$$\left\{ \int_a^b \frac{dx}{(x-a)^n} \text{ is convergent iff } n < 1 \right\}$$

By comparison test,

$$\int_0^1 f(x) dx = \int_0^1 x^{n-1} \cdot e^{-x} dx \text{ is convergent iff } 1-n < 1, \text{ i.e., } n > 0 \text{ at } x=0.$$

Convergence at $x=\infty$

Let $g(x) = \frac{1}{x^p}$, so that,

$$\left\{ \int_a^\infty \frac{dx}{x^p} \text{ is convergent iff } p > 1 (a > 0) \right\}$$

$$f(x) = x^{n-1} \cdot e^{-x}$$

$$\lim_{x \rightarrow \infty} \frac{f(x)}{g(x)} = \lim_{x \rightarrow \infty} \frac{x^{n+1}}{e^x} = 0 \text{ for all } n. \left\{ \begin{array}{l} \text{L'Hospital,} \\ \lim_{x \rightarrow \infty} \frac{(n+1)n(n-1) \dots 1}{e^x} = 0 \end{array} \right\}$$

$$\text{As, } \int_1^\infty g(x) dx = \int_1^\infty \frac{1}{x^2} dx \text{ converges, here,}$$

$$\int_1^\infty f(x) dx = \int_1^\infty x^{n-1} \cdot e^{-x} dx \text{ also converges for all } n.$$

Properties of Gamma Function

1) $\Gamma(n+1) = n\Gamma(n)$, $n > 0$.

Proof: $\Gamma(n) = \int_0^{\infty} x^{n-1} \cdot e^{-x} \cdot dx$

$$\Gamma(n+1) = \int_0^{\infty} x^n \cdot e^{-x} \cdot dx = \lim_{m \rightarrow \infty} \int_0^m x^n \cdot e^{-x} \cdot dx \quad \left\{ \begin{array}{l} u = x^n \Rightarrow n x^{n-1} dx = du \\ e^{-x} dx = dv \Rightarrow v = -e^{-x} \end{array} \right\}$$

$$= \lim_{m \rightarrow \infty} \left(-x^n \cdot e^{-x} \Big|_0^m + n \int_0^m x^{n-1} \cdot e^{-x} \cdot dx \right)$$

$$= \lim_{m \rightarrow \infty} \left(\underbrace{-x^n \cdot e^{-x} \Big|_0^m}_{-m^n \cdot e^{-m}} + n \underbrace{\int_0^{\infty} x^{n-1} \cdot e^{-x} \cdot dx}_{\Gamma(n)} \right)$$

$$= \lim_{m \rightarrow \infty} \underbrace{(-m^n \cdot e^{-m})}_0 + n\Gamma(n)$$

$$\Gamma(n+1) = n\Gamma(n) \quad \checkmark$$

2) $\Gamma(n+1) = n!$, $n = 1, 2, 3, \dots$

Proof: $\Gamma(n+1) = n\Gamma(n) = n\Gamma(n-1+1)$

$$= n(n-1)\Gamma(n-1) = n(n-1)\Gamma(n-2+1) \\ = n(n-1)(n-2)\Gamma(n-2)$$

$$\vdots \\ = n(n-1)(n-2) \dots \Gamma(1)$$

$$\left\{ \Gamma(1) = \int_0^{\infty} e^{-x} dx = -e^{-x} \Big|_0^{\infty} = 1 \right\}$$

$$= n(n-1)(n-2) \dots 1$$

$$\Gamma(n+1) = n! \quad \checkmark$$

Ex: i) $\frac{\Gamma(6)}{2\Gamma(3)} = \frac{5!}{2 \cdot 2!} = 30$

ii) $\Gamma(10) = 9!$

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3) $\Gamma(1/2) = \sqrt{\pi}$

4) $\Gamma(n) = \frac{\Gamma(n+1)}{n}, n < 0$

Ex: $\Gamma(-1/2) = \frac{\Gamma(-1/2+1)}{-1/2} = -2\Gamma(1/2) = -2\sqrt{\pi}$

$$\Gamma(-5/2) = \frac{\Gamma(-5/2+1)}{-5/2} = -\frac{2}{5}\Gamma(-3/2) = -\frac{2}{5}\frac{\Gamma(-3/2+1)}{-3/2} = \frac{4}{15}\Gamma(-1/2) = -\frac{8}{15}\sqrt{\pi}$$

5) $\Gamma(n+1/2) = \frac{(2n)! \sqrt{\pi}}{4^n \cdot n!}$

6) $\Gamma(n+k) = n(n+1)(n+2)\dots(n+k-1)\Gamma(n)$, k is a positive integer.

$\Gamma(n+1) = n\Gamma(n)$

$\Gamma(n+2) = (n+1)\Gamma(n+1) = (n+1) \cdot n \cdot \Gamma(n)$

$\vdots$

7) $\Gamma(p)\Gamma(1-p) = \frac{\pi}{\sin p\pi}, 0 < p < 1$

$$\begin{aligned} \Gamma(n+k-1+1) &= (n+k-1) \frac{\Gamma(n+k-1)}{\Gamma(n+k-2+1) \Gamma(n+k-2)} \\ &= (n+k-1) \Gamma(n+k-2) \frac{\Gamma(n+k-2)}{\Gamma(n+k-3+1) \Gamma(n+k-3)} \\ &= (n+k-1) \Gamma(n+k-2) \dots (n+k-(k-1)) \Gamma(n+k-(k-1)+1) \\ &= (n+k-1) \Gamma(n+k-2) \dots (n+1) \frac{\Gamma(n+1)}{n \Gamma(n)} \end{aligned}$$

Ex: $p = \frac{3}{4}, 1-p = \frac{1}{4} \Rightarrow \Gamma(3/4)\Gamma(1/4) = \frac{\pi}{\sin \frac{3\pi}{4}} = \sqrt{2}\pi$

8) Asymptotic formula for $\Gamma(n)$:

If n is large, the computational difficulties in a calculation of $\Gamma(n)$ are appeared. A useful result in such case is supplied by the relation,

$$\Gamma(n+1) = \sqrt{2\pi \cdot n} \cdot n^n \cdot e^{-n} \cdot e^{\frac{\theta}{12(n+1)}}, 0 < \theta < 1$$

for most practical purposes the last factor $(e/12(n+1))$ which is very close to 1, for large n can be omitted. If n is integer, we can write,

$$\Gamma(n+1) = n! \sim \sqrt{2\pi n} \cdot n^n \cdot e^{-n}$$

Stirling's factorial approximation or asymptotic formula for large n .

Ex: $5! \sim \sqrt{2\pi} \cdot 5^5 \cdot e^{-5} = 118.02$.

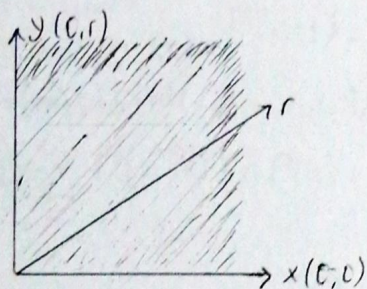
Ex:

Prove that $I = \int_0^{\infty} e^{-x^2} dx = \frac{\sqrt{\pi}}{2}$.

$$I = \int_0^{\infty} e^{-y^2} dy \Rightarrow I^2 = \left(\int_0^{\infty} e^{-x^2} dx \right) \left(\int_0^{\infty} e^{-y^2} dy \right) = \int_0^{\infty} \int_0^{\infty} e^{-(x^2+y^2)} dx dy$$

Use polar coordinates:

$$\begin{aligned} x &= r \cos \theta \\ y &= r \sin \theta \\ dA &= r dr d\theta \end{aligned} \quad \left\{ \begin{array}{l} r; \\ (x, y) \rightarrow (r, \theta) \\ J(r, \theta) = r \end{array} \right\}$$



$$\Rightarrow I^2 = \int_{\theta=0}^{\pi/2} \left(\int_{r=0}^{\infty} e^{-r^2} r dr \right) d\theta$$

$$\left\{ \begin{array}{l} r^2 = u \\ 2r dr = du \end{array} \Rightarrow \int_0^{\infty} e^{-u} \cdot \frac{du}{2} = -\frac{1}{2} e^{-u} \Big|_0^{\infty} = \frac{1}{2} \right\}$$

$$\Rightarrow I^2 = \int_{\theta=0}^{\pi/2} \frac{1}{2} d\theta = \frac{\pi}{4} \Rightarrow I = \frac{\sqrt{\pi}}{2}$$

✓ 2nd method:

$$\Gamma(n) = \int_0^{\infty} x^{n-1} \cdot e^{-x} \cdot dx, \quad n > 0$$

$$I = \int_0^{\infty} e^{-x^2} dx \quad \left\{ \begin{array}{l} y = x^2 \Rightarrow dy = 2x dx \\ x=0 \Rightarrow y=0 \\ x=\infty \Rightarrow y=\infty \end{array} \right\}$$

$$= \int_0^{\infty} e^{-y} \frac{dy}{2y^{1/2}} = \frac{1}{2} \int_0^{\infty} y^{-1/2} e^{-y} dy = \frac{1}{2} \Gamma(1/2) = \frac{\sqrt{\pi}}{2}$$

($n-1 = -1/2 \Rightarrow \Gamma(1/2)$)

Ex: Show that $\Gamma(1/2) = \sqrt{\pi}$. (3rd property of $\Gamma(n)$)

$$\Gamma(n) = \int_0^{\infty} x^{n-1} e^{-x} dx, \quad n > 0$$

$$\Gamma(1/2) = \int_0^{\infty} x^{-1/2} e^{-x} dx \quad \left\{ \begin{array}{l} x = u^2 \Rightarrow dx = 2u du \\ x=0 \Rightarrow u=0 \\ x=\infty \Rightarrow u=\infty \end{array} \right\}$$

$$= \int_0^{\infty} u^{-1} e^{-u^2} \cdot 2u du = 2 \int_0^{\infty} e^{-u^2} du = 2 \cdot \frac{\sqrt{\pi}}{2} = \sqrt{\pi}$$

Ex: Evaluate each integral

i) $\int_0^{\infty} \sqrt{y} \cdot e^{-y^3} dy$

ii) $\int_0^{\infty} 3^{-4x^2} dx$

iii) $\int_0^1 \frac{dx}{\sqrt{-\ln x}}$

i) $\int_0^{\infty} y^{1/3} e^{-y^3} dy \quad \left\{ \begin{array}{l} y = x^{1/3} \Rightarrow y^3 = x \Rightarrow 3y^2 dy = dx \\ x=0 \Rightarrow y=0 \\ x=\infty \Rightarrow y=\infty \end{array} \right\}$

$$= \int_0^{\infty} (x^{1/3})^{1/2} \cdot e^{-x} \cdot \frac{dx}{3x^{2/3}} = \frac{1}{3} \int_0^{\infty} x^{-1/2} e^{-x} dx = \frac{1}{3} \Gamma(1/2) = \frac{\sqrt{\pi}}{3}$$

ii) $3^{-4x^2} = e^{\ln 3^{-4x^2}} = e^{-(4x^2 \ln 3)}$

$$\left\{ \begin{array}{l} y = 4x^2 \ln 3 \Rightarrow dy = 8x \ln 3 dx \\ dx = \frac{dy}{8x \ln 3} \Rightarrow dx = \frac{dy}{(8 \ln 3)(4 \ln 3)^{1/2} y^{1/2}} \\ x=0 \Rightarrow y=0 \\ x=\infty \Rightarrow y=\infty \end{array} \right\}$$

$$\begin{aligned}
 \Rightarrow \int_0^{\infty} 3^{-4x^2} dx &= \int_0^{\infty} e^{\ln(3^{-4x^2})} dx = \int_0^{\infty} e^{-(4x^2 \ln 3)} dx \\
 &= \int_0^{\infty} e^{-y} \cdot \frac{dy}{(8 \ln 3)(4 \ln 3)^{-1/2}} \cdot y^{-1/2} \\
 &= \int_0^{\infty} e^{-y} \cdot y^{-1/2} \cdot dy \cdot \frac{1}{(8 \ln 3)(4 \ln 3)^{-1/2}} = \Gamma(1/2) \cdot \frac{1}{(8 \ln 3)(4 \ln 3)^{-1/2}} \\
 &= \frac{\sqrt{\pi}}{4(\ln 3)^{1/2}}
 \end{aligned}$$

iii) - $\{ \ln x = y \quad \left\{ \begin{array}{l} x = e^{-y} \Rightarrow dx = -e^{-y} dy \\ x = 0 \Rightarrow y = \infty \\ x = 1 \Rightarrow y = 0 \end{array} \right. \}$

$$\Rightarrow \hat{I} = \int_{\infty}^0 \frac{1}{\sqrt{y}} (-e^{-y}) dy = \int_0^{\infty} y^{-1/2} \cdot e^{-y} dy = \Gamma(1/2) = \sqrt{\pi}$$

Beta Function

Definition! If $m, n > 0$ then the integral,

$$\int_0^1 x^{m-1} \cdot (1-x)^{n-1} dx$$

which is obviously a function of m and n , is called a Beta function, and is denoted by; $\beta(m, n)$. Thus,

$$\beta(m, n) = \int_0^1 x^{m-1} \cdot (1-x)^{n-1} dx, \quad m, n > 0.$$

Beta Function is called the first Eulerian integral. For example;

i) $\int_0^1 x^3 (1-x)^5 dx = \beta(4, 6)$

ii) $\int_0^1 \sqrt{x} \cdot (1-x)^3 dx = \beta(3/2, 4)$

iii) $\int_0^1 x^{-2/3} \cdot (1-x)^{1/2} dx = \beta(1/3, 1/2)$

iv) $\int_0^1 x^{-3} \cdot (1-x)^5 dx = \beta(-2, 6)$ is not β function.

Convergence of Beta FunctionTheorem:

$$\int_0^1 x^{m-1} \cdot (1-x)^{n-1} dx \text{ exists iff } m \text{ and } n \text{ are both positive.}$$

Proof: If $m \geq 1$ and $n \geq 1$, then the integral is proper.

If $m < 1$ and $n < 1$, then $f(x) = \frac{1}{x^{1-m} \cdot (1-x)^{1-n}}$.

For $m < 1$ and $n < 1$,

$$\int_0^1 x^{m-1} (1-x)^{n-1} dx = \underbrace{\int_0^{1/2} x^{m-1} (1-x)^{n-1} dx}_{\substack{\text{infinite} \\ \text{discontinuity} \\ x=0}} + \underbrace{\int_{1/2}^1 x^{m-1} (1-x)^{n-1} dx}_{\substack{\text{infinite} \\ \text{discontinuity} \\ x=1}}$$

Convergence at $x=0$ when $m < 1$:

Let $f(x) = \frac{(1-x)^{n-1}}{x^{1-m}}$, take $g(x) = \frac{1}{x^{1-m}}$

$$\lim_{x \rightarrow 0^+} \frac{f(x)}{g(x)} = \lim_{x \rightarrow 0^+} (1-x)^{n-1} = 1, \text{ which is nonzero, } \cancel{\text{finite}}$$

$$\int_0^{1/2} g(x) dx = \int_0^{1/2} \frac{dx}{x^{1-m}} \text{ is convergent iff } 1-m < 1, \text{ i.e., } m > 0.$$

By comparison test,

$$\int_0^{1/2} f(x) dx = \int_0^{1/2} x^{m-1} (1-x)^{n-1} dx \text{ is also convergent at } x=0 \text{ for } m > 0.$$

Convergence at $x=1$, when $n < 1$:

Let $f(x) = \frac{x^{m-1}}{(1-x)^{1-n}}$. take $g(x) = \frac{1}{(1-x)^{1-n}}$

$$\lim_{x \rightarrow 1^-} \frac{f(x)}{g(x)} = \lim_{x \rightarrow 1^-} x^{m-1} = 1 \text{ which is nonzero, finite.}$$

$$\int_{1/2}^1 g(x) dx = \int_{1/2}^1 \frac{dx}{(1-x)^{1-n}} \text{ is convergent } 1-n < 1, \text{ i.e., } n > 0.$$

By comparison test,

$$\int_{1/2}^1 f(x) dx = \int_{1/2}^1 x^{m-1} \cdot (1-x)^{n-1} dx \text{ is convergent at } x=1 \text{ for } n > 0.$$

$$\int_0^1 x^{m-1} \cdot (1-x)^{n-1} dx = \underbrace{\int_0^{1/2} x^{m-1} \cdot (1-x)^{n-1} dx}_{m < 1} + \underbrace{\int_{1/2}^1 x^{m-1} \cdot (1-x)^{n-1} dx}_{n < 1}, \quad m, n > 0$$

Properties of Beta Function

1) $\beta(m, n) = \int_0^1 x^{m-1} \cdot (1-x)^{n-1} dx, \quad m > 0, n > 0.$

$$\beta(m, n) = \beta(n, m)$$

Proof: Use transformation $x=1-y$.

$$\left. \begin{array}{l} x=1-y \Rightarrow dx = -dy \\ x=0 \Rightarrow y=1 \\ x=1 \Rightarrow y=0 \end{array} \right\} \Rightarrow \beta(m, n) = \int_1^0 (1-y)^{m-1} \cdot (1-(1-y))^{n-1} \cdot (-dy)$$

$$= \int_0^1 y^{n-1} \cdot (1-y)^{m-1} dy = \beta(n, m) \quad \checkmark$$

$\left(\begin{array}{l} m-1 = n-1 \Rightarrow m=n \\ n-1 = m-1 \Rightarrow n=m \end{array} \right)$

$$2) \quad \beta(m, n) = 2 \int_0^{\pi/2} \sin^{2m-1} \theta \cdot \cos^{2n-1} \theta \cdot d\theta$$

Proof: Use transformation $x = \sin^2 \theta$.

$$\left. \begin{array}{l} x = \sin^2 \theta \Rightarrow dx = 2 \sin \theta \cos \theta d\theta \\ x = 0 \Rightarrow \theta = 0 \\ x = 1 \Rightarrow \theta = \pi/2 \end{array} \right\} \Rightarrow \beta(m, n) = \int_0^{\pi/2} \sin^{2m-2} \theta \cdot \underbrace{(1 - \sin^2 \theta)^{n-1}}_{\cos^2 \theta} \cdot 2 \sin \theta \cos \theta d\theta$$

$$= 2 \int_0^{\pi/2} \sin^{2m-1} \theta \cdot \cos^{2n-1} \theta d\theta. \quad \checkmark$$

$$3) \quad \beta(m, n) = \frac{\Gamma(m) \cdot \Gamma(n)}{\Gamma(m+n)}$$

Proof: Use transformation $z = x^2$.

$$\left\{ \Gamma(m) = \int_0^{\infty} z^{m-1} \cdot e^{-z} \cdot dz, m > 0 \right\}$$

$$\left\{ \begin{array}{l} z = x^2 \Rightarrow dz = 2x dx \\ 0 \leq z < \infty \end{array} \right\} \Rightarrow \Gamma(m) = \int_0^{\infty} x^{2m-2} \cdot e^{-x^2} \cdot 2x dx = 2 \int_0^{\infty} x^{2m-1} \cdot e^{-x^2} dx$$

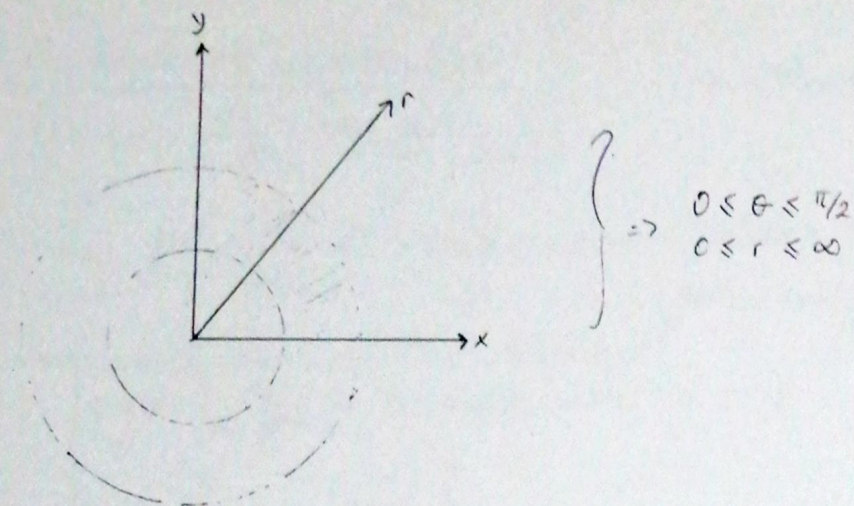
$$\Gamma(n) = 2 \int_0^{\infty} y^{2n-1} \cdot e^{-y^2} dy$$

$$\Gamma(m) \cdot \Gamma(n) = \left(2 \int_0^{\infty} x^{2m-1} \cdot e^{-x^2} dx \right) \left(2 \int_0^{\infty} y^{2n-1} \cdot e^{-y^2} dy \right)$$

$$= 4 \int_0^{\infty} \int_0^{\infty} x^{2m-1} \cdot y^{2n-1} \cdot e^{-(x^2+y^2)} dx dy$$

Use polar coordinates:

$$\left\{ \begin{array}{l} x = r \cos \theta \\ y = r \sin \theta \\ dA = |J(r, \theta)| dr d\theta = r dr d\theta \end{array} \right\} \quad \begin{array}{l} 0 \leq \theta < \pi/2 \\ 0 \leq r < \infty \end{array}$$



$$\Rightarrow 4 \int_{\theta=0}^{\pi/2} \int_{r=0}^{\infty} r^{2m-1} \cdot \cos^{2m-1} \theta \cdot r^{2n-1} \cdot \sin^{2n-1} \theta \cdot e^{-r^2} \cdot r \, dr \, d\theta$$

$$= 4 \left(\frac{1}{2} \cdot 2 \int_0^{\pi/2} \sin^{2n-1} \theta \cdot \cos^{2m-1} \theta \, d\theta \right) \left(\int_0^{\infty} r^{2(m+n)-1} \cdot e^{-r^2} \, dr \right)$$

$$\frac{1}{2} \beta(m, n)$$

$$\left. \begin{array}{l} r^2 = u \Rightarrow 2r \, dr = du \\ r = 0 \Rightarrow u = 0 \\ r = \infty \Rightarrow u = \infty \end{array} \right\} \Rightarrow \int_0^{\infty} u^{m+n-1/2} \cdot e^{-u} \cdot \frac{du}{2u^{1/2}}$$

$$= \frac{1}{2} \int_0^{\infty} u^{m+n-1} \cdot e^{-u} \cdot du$$

$\Gamma(m+n)$

$$\Rightarrow \Gamma(m) \cdot \Gamma(n) = 4 \cdot \left(\frac{1}{2} \beta(m, n) \right) \left(\frac{1}{2} \Gamma(m+n) \right) \cdot$$

$$\beta(m, n) = \frac{\Gamma(m) \cdot \Gamma(n)}{\Gamma(m+n)} \quad \checkmark$$

4)

$$\beta(m, n) = \int_0^{\infty} \frac{x^{m-1}}{(1+x)^{m+n}} \cdot dx, \quad m, n > 0.$$

Proof: Use transformation $z = \frac{x}{1+x} \left(x = \frac{z}{1-z} \right)$

$$\left\{ \beta(m, n) = \int_0^1 z^{m-1} (1-z)^{n-1} dz, \quad m, n > 0 \right\}$$

$$\left. \begin{array}{l} z = \frac{x}{1+x} \Rightarrow dz = \frac{dx}{(1+x)^2} \\ z=0 \Rightarrow x=0 \\ z=1 \Rightarrow x=\infty \end{array} \right\} \Rightarrow \beta(m, n) = \int_{x=0}^{\infty} \left(\frac{x}{1+x} \right)^{m-1} \cdot \left(1 - \frac{x}{1+x} \right)^{n-1} \cdot \frac{dx}{(1+x)^2}$$

$$= \int_0^{\infty} \frac{x^{m-1}}{(1+x)^{m-1}} \cdot \frac{1}{(1+x)^{n-1}} \cdot \frac{dx}{(1+x)^2}$$

$$= \int_0^{\infty} \frac{x^{m-1}}{(1+x)^{m+n}} dx \quad \checkmark$$

5)

$$\beta(p, 1-p) = \frac{\Gamma(p) \Gamma(1-p)}{\Gamma(1)} = \Gamma(p) \Gamma(1-p) = \frac{\pi}{\sin p\pi}$$

$$= \int_0^{\infty} \frac{x^{p-1}}{(1+x)} dx \quad \left\{ \begin{array}{l} 0 < p < 1 \\ m=p \\ n=1-p \end{array} \right\}$$

Ex: Evaluate each of the following integrals.

i) $\int_0^1 x^4 (1-x)^2 dx$

ii) $\int_0^2 \frac{x^2 dx}{\sqrt{2-x}}$

iii) $\int_0^a y^4 \sqrt{a^2 - y^2} dy$

i) $\beta(5, 3) = \frac{\Gamma(5) \cdot \Gamma(3)}{\Gamma(8)} = \frac{4! \cdot 2!}{7!} = \frac{1}{105}$

ii) $\int_0^2 x^2 (2-x)^{-1/2} dx \quad \left\{ \begin{array}{l} x=2y \Rightarrow dx=2dy \\ x=0 \Rightarrow y=0 \\ x=2 \Rightarrow y=1 \end{array} \right\}$

$$\Rightarrow \int_0^1 (2y)^2 (2-2y)^{-1/2} dy \cdot 2 = \int_0^1 4\sqrt{2} \cdot y^2 (1-y)^{-1/2} dy$$

$$\left(\begin{array}{l} m-1=2 \Rightarrow m=3 \\ n-1=-1/2 \Rightarrow n=1/2 \end{array} \right) \Rightarrow 4\sqrt{2} \cdot \beta(3, 1/2) = 4\sqrt{2} \cdot \frac{\Gamma(3) \cdot \Gamma(1/2)}{\Gamma(7/2)}$$

$$= 4\sqrt{2} \cdot \frac{2! \cdot \sqrt{\pi}}{\Gamma(7/2)}$$

$$\left\{ \begin{array}{l} \Gamma(n+1/2) = \frac{(2n)! \cdot \sqrt{\pi}}{4^n \cdot n!} \\ \Gamma(3+1/2) = \frac{6! \cdot \sqrt{\pi}}{4^3 \cdot 3!} = \frac{15\sqrt{\pi}}{8} \end{array} \right\}$$

$$= 4\sqrt{2} \cdot \frac{2! \cdot \sqrt{\pi}}{\frac{15\sqrt{\pi}}{8}} = \frac{64\sqrt{2}}{15}$$

iii) Use transformation $y^2 = a^2 x$ or $y = a \sin t$.

$$\left\{ \text{Result: } \frac{\pi a^6}{16} \right\}$$

Ex: Evaluate each integrals.

$$i) \int_0^{\pi/2} \sin^6 \theta d\theta$$

$$ii) \int_1^3 \frac{x dx}{\sqrt{(x-1)(3-x)}}$$

$$iii) \int_0^{\pi} \cos^6 \theta d\theta$$

$$i) \int_0^{\pi/2} \sin^6 \theta d\theta = \frac{1}{2} \cdot 2 \int_0^{\pi/2} \sin^6 \theta \cdot \cos^0 \theta d\theta$$

$$\left(\begin{array}{l} 2m-1=6 \Rightarrow m=7/2 \\ 2n-1=0 \Rightarrow n=1/2 \end{array} \right) \Rightarrow \frac{1}{2} \cdot \beta(7/2, 1/2) = \frac{1}{2} \cdot \frac{\Gamma(7/2) \Gamma(1/2)}{\Gamma(4)}$$

$$= \frac{1}{2} \cdot \frac{15\sqrt{\pi}/8 \cdot \sqrt{\pi}}{3!}$$

$$= \frac{5\pi}{32}$$

ii) Use transformation $x-1=u$ ($u+1=x$)

$$\left. \begin{array}{l} x-1=u \Rightarrow dx=du \\ x=1 \Rightarrow u=0 \\ x=3 \Rightarrow u=2 \end{array} \right\} \Rightarrow \int_0^2 \frac{du}{\sqrt{u(2-u)}} = \int_0^2 u^{-1/2} \cdot (2-u)^{-1/2} du$$

1 division

$$\left. \begin{array}{l} u=2x \\ du=2dx \\ u=0 \Rightarrow x=0 \\ u=2 \Rightarrow x=1 \end{array} \right\} \Rightarrow \int_0^1 (2x)^{-1/2} \cdot (2-2x)^{-1/2} \cdot 2dx$$

2 division

$$= \int_0^1 2^{-1/2} \cdot x^{-1/2} \cdot 2^{-1/2} \cdot (1-x)^{-1/2} \cdot 2dx$$

$$= \int_0^1 x^{-1/2} \cdot (1-x)^{-1/2} dx$$

$$\left(\begin{array}{l} m-1 = -1/2 \Rightarrow m = 1/2 \\ n-1 = -1/2 \Rightarrow n = 1/2 \end{array} \right) \Rightarrow \beta(1/2, 1/2) = \frac{\Gamma(1/2) \cdot \Gamma(1/2)}{\Gamma(1)} = \pi$$

vega file division:

$$x-1=2u \quad x=1 \Rightarrow u=0$$

$$dx=2du \quad x=3 \Rightarrow u=1$$

$$I = \int_0^1 \frac{2du}{\sqrt{2u} \cdot \sqrt{2-2u}} = \int_0^1 \frac{1}{u^{1/2} \cdot (1-u)^{1/2}} du$$

$$3-x = 3-(1+2u) = 2-2u$$

iii)

$$\int_0^\pi \cos^6 \theta d\theta = \int_0^{\pi/2} \cos^6 \theta d\theta + \int_{\pi/2}^\pi \cos^6 \theta d\theta$$

*

* : Use transformation $\theta = \pi - x$.

$$\left. \begin{array}{l} \theta = \pi - x \Rightarrow d\theta = -dx \\ \theta = \pi/2 \Rightarrow x = \pi/2 \\ \theta = \pi \Rightarrow x = 0 \end{array} \right\} \Rightarrow * = \int_{\pi/2}^0 \cos^6 \theta d\theta = \int_{\pi/2}^0 \cos^6(\pi-x) (-dx)$$

$$\left\{ \begin{array}{l} \cos(\pi-x) = \cos \pi \cdot \cos x + \sin \pi \cdot \sin x = -\cos x \end{array} \right\}$$

$$= \int_0^{\pi/2} \cos^6 x dx \Rightarrow \int_0^{\pi/2} \cos^6 \theta d\theta$$

$$\Rightarrow \int_0^{\pi} \cos^6 \theta d\theta = \int_0^{\pi/2} \cos^6 \theta d\theta + \int_{\pi/2}^{\pi} \cos^6 \theta d\theta = 2 \int_0^{\pi/2} \cos^6 \theta d\theta$$

$$= 2 \int_0^{\pi/2} \sin^0 \theta \cdot \cos^6 \theta d\theta$$

$$\left(\begin{array}{l} 2m-1=0 \Rightarrow m=1/2 \\ 2n-1=6 \Rightarrow n=7/2 \end{array} \right) = \beta(1/2, 7/2) = \frac{\Gamma(1/2) \Gamma(7/2)}{\Gamma(4)}$$

$$= \frac{\sqrt{\pi} \cdot \frac{15\sqrt{\pi}}{8}}{3!} = \frac{5\pi}{16}$$

$$\left\{ \begin{array}{l} \text{If } \int_0^{2\pi} \dots = \int_0^{\pi} \dots + \int_{\pi}^{2\pi} \dots \text{ then use transformation } \theta = 2\pi - x. \end{array} \right\}$$

HW:

$$i) \int_0^{\infty} \frac{dy}{1+y^4} = ? \quad \left\{ \text{Result} = \frac{\sqrt{2} \cdot \pi}{4} \right\}$$

$$ii) \int_0^2 x \cdot \sqrt[3]{8-x^3} \cdot dx = ? \quad \left\{ \text{Result} = \frac{16\pi}{9\sqrt{3}} \right\}$$

VECTOR FIELDS, VECTOR CALCULUS

Vector and Scalar Fields

A function whose domain and range are subsets of $\mathbb{R}^3$ is called a vector field.

$$\vec{F}(x, y, z) = \underbrace{f_1(x, y, z)}_{\substack{\text{Components of vector field} \\ \text{(Scalar values)}}} \vec{i} + \underbrace{f_2(x, y, z)}_{\substack{\text{Components of vector field} \\ \text{(Scalar values)}}} \vec{j} + \underbrace{f_3(x, y, z)}_{\substack{\text{Components of vector field} \\ \text{(Scalar values)}}} \vec{k}$$

If $F_3(x, y, z) = 0$ and F_1 and F_2 are independent of z , then $\vec{F}$ reduces to,

$$\vec{F}(x, y) = F_1(x, y)\vec{i} + F_2(x, y)\vec{j}$$

plane vector field (or vector field in the xy -plane). The position of vector of (x, y, z) ,

$$\vec{r}(x, y, z) = x\vec{i} + y\vec{j} + z\vec{k}.$$

Gradient, Divergence and Curl (or Rotational) (Rot)

$$\checkmark \text{ grad } f(x, y, z) = \nabla f(x, y, z) = \frac{\partial f}{\partial x}\vec{i} + \frac{\partial f}{\partial y}\vec{j} + \frac{\partial f}{\partial z}\vec{k} \quad \left\{ \begin{array}{l} \nabla = \frac{\partial}{\partial x}\vec{i} + \frac{\partial}{\partial y}\vec{j} + \frac{\partial}{\partial z}\vec{k} \text{ (Vector-Differentiate)} \\ \downarrow \text{ Operator} \\ \text{Nabla (or Del)} \end{array} \right\}$$

$$\begin{aligned} \checkmark \text{ div } \vec{F} = \nabla \cdot \vec{F} &= \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} \\ &= \left(\frac{\partial}{\partial x}\vec{i} + \frac{\partial}{\partial y}\vec{j} + \frac{\partial}{\partial z}\vec{k} \right) \cdot \underbrace{(F_1\vec{i} + F_2\vec{j} + F_3\vec{k})}_{\vec{F}} \end{aligned}$$

$$\begin{aligned} \checkmark \text{ Curl } \vec{F} = \text{Rot } \vec{F} = \nabla \times \vec{F} &= \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} \\ &= \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right)\vec{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right)\vec{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right)\vec{k} \end{aligned}$$

$$\checkmark \nabla^2 = \nabla \cdot \nabla \Rightarrow \text{Laplacian Operator} \quad \left(\nabla^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right)$$

ϕ : Scalar field

$\vec{F}$: Vector field

$$\nabla^2 \phi = \nabla \cdot \nabla \phi = \text{div}(\text{grad } \phi) = \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \phi$$

$$\nabla^2 \vec{F} = \nabla^2 (F_1\vec{i} + F_2\vec{j} + F_3\vec{k}) = \nabla^2 F_1\vec{i} + \nabla^2 F_2\vec{j} + \nabla^2 F_3\vec{k} = \left(\frac{\partial^2 F_1}{\partial x^2} + \frac{\partial^2 F_1}{\partial y^2} + \frac{\partial^2 F_1}{\partial z^2} \right)\vec{i} + \left(\frac{\partial^2 F_2}{\partial x^2} + \frac{\partial^2 F_2}{\partial y^2} + \frac{\partial^2 F_2}{\partial z^2} \right)\vec{j} + \left(\frac{\partial^2 F_3}{\partial x^2} + \frac{\partial^2 F_3}{\partial y^2} + \frac{\partial^2 F_3}{\partial z^2} \right)\vec{k}$$

$$\Rightarrow \nabla \cdot (\nabla \times \vec{F}) = 0 \quad (\text{div}(\text{curl}) = 0)$$

$$\Rightarrow \nabla \times (\nabla \phi) = 0 \quad (\text{Curl}(\text{grad}) = 0)$$

Irrotational Vector Fields

A vector field $\vec{F}$ is called irrotational in a domain D if $\text{Curl } \vec{F} = 0$ in D .

$$\vec{F} = \text{grad } \phi \iff \text{Curl } \vec{F} = 0$$

✓ Every conservative vector field is irrotational. (ϕ : Potential Function)

Integration in Vector Fields

Line integrals are used to find the work done by a force in moving an object along a path and to find the mass of curved wire with variable density. Surface integrals are used to find the rate of flow of a fluid across a surface.

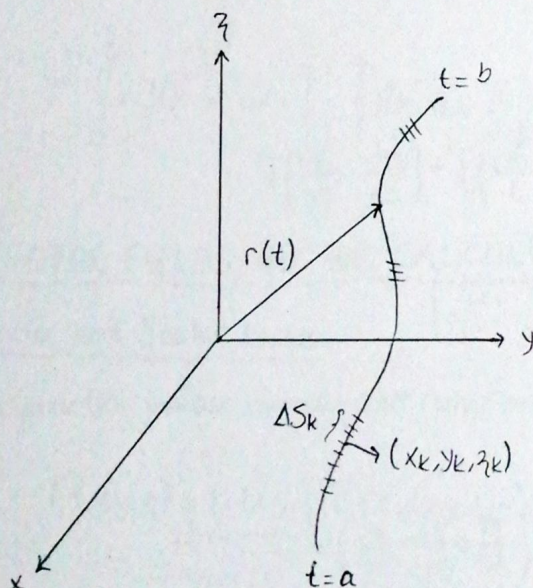
Line Integral

We need to integrate over a curve C rather than over an interval $[a, b]$. We make our definitions for space curves and the curves in the xy -plane.

Suppose that $f(x, y, z)$ is a real valued function. We wish to integrate over the curve C lying within the domain of f and parametrized by,

$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}, \quad a \leq t \leq b.$$

The values of f along the curve are given by $f(x(t), y(t), z(t))$. We are going to integrate this function with respect to arc length from $t=a$ to $t=b$. To begin, we first partition the curve C into a finite number n of subarcs. (Fig. 1)



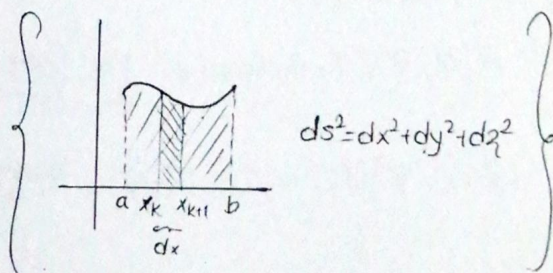
- Figure 1 -

The curve $f(t)$ partitioned into small arcs from $t=a$ to $t=b$. The typical subarc is ΔS_k .

In each subarc we choose a point (x_k, y_k, z_k) and form the sum,

$$S_n = \sum_{k=1}^n f(x_k, y_k, z_k) \Delta S_k$$

which is similar to Riemann Sum.



If f is continuous and the functions $x(t), y(t), z(t)$ have continuous first order derivatives then these sums approach a limit as n increases and the length ΔS_k approaches to zero.

$$n \rightarrow \infty, \Delta S_k \rightarrow 0.$$

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Definition: If f is defined on a curve c given parametrically by,

$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}, \quad a \leq t \leq b$$

then the integral of f over c is,

$$\int_c f(x, y, z) ds = \lim_{\substack{n \rightarrow \infty \\ (\Delta S_k \rightarrow 0)}} \sum_{k=1}^n f(x_k, y_k, z_k) \Delta S_k$$

provided the limit exists.

$$ds^2 = dx^2 + dy^2 + dz^2 \Rightarrow \frac{ds}{dt} = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2}$$

$$\frac{d\vec{r}}{dt} = \frac{dx}{dt}\vec{i} + \frac{dy}{dt}\vec{j} + \frac{dz}{dt}\vec{k} \Rightarrow \left|\frac{d\vec{r}}{dt}\right| = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2}$$

$$ds = \left|\frac{d\vec{r}}{dt}\right| dt$$

How to Evaluate a Line Integral

To integrate a continuous function $f(x, y, z)$ over a curve c ,

1) Find a smooth parametrization of c .

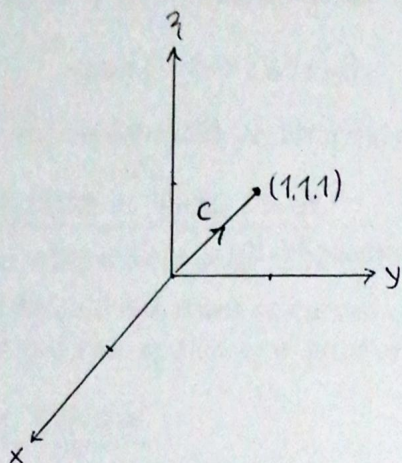
$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}, \quad a \leq t \leq b$$

2) Evaluate the integral as,

$$\int_c f(x, y, z) ds = \int_a^b f(x(t), y(t), z(t)) \left|\frac{d\vec{r}}{dt}\right| dt$$

* If f has the constant value 1, then the integral of f over c gives the length of the c from $t=a$ to $t=b$ (Fig 1)

Ex: Integrate $f(x,y,z) = x - 3y^2 + z$ over the line segment c joining the origin to the point $(1,1,1)$.



$$\int_c f(x,y,z) ds = \int_a^b f(x(t), y(t), z(t)) \left| \frac{d\vec{r}}{dt} \right| dt = ?$$

$$c: \begin{cases} x=t \\ y=t \\ z=t \end{cases} \quad \begin{matrix} (0,0,0) \rightarrow (1,1,1) \\ t=0 \rightarrow t=1 \end{matrix} \quad \left\{ \begin{array}{l} \frac{x-x_0}{x_1-x_0} = \frac{y-y_0}{y_1-y_0} = \frac{z-z_0}{z_1-z_0} = t, \quad -\infty < t < \infty \\ \text{(Parametric form of the line equation)} \end{array} \right\}$$

$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$$

$$\vec{r}(t) = t\vec{i} + t\vec{j} + t\vec{k} \Rightarrow \frac{d\vec{r}}{dt} = \vec{i} + \vec{j} + \vec{k}$$

$$\Rightarrow ds = \sqrt{1^2 + 1^2 + 1^2} dt = \sqrt{3} dt \quad (0 \leq t \leq 1)$$

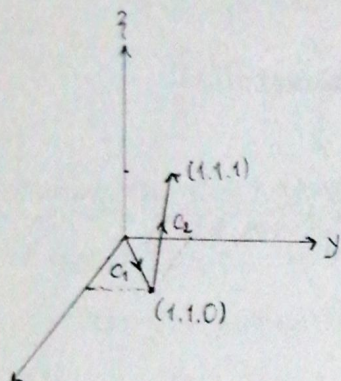
$$f(t,t,t) = t - 3t^2 + t = 2t - 3t^2 \Rightarrow \int_0^1 (2t - 3t^2) \sqrt{3} dt = \sqrt{3} (t^2 - t^3) \Big|_0^1 = 0.$$

Additivity

Line integrals have the useful property that if a piecewise smooth curve c is made by joining a finite number of smooth curves $c_1, c_2, \dots, c_n$ end to end, then the integral of a function over c is the sum of the integrals over the curves that make it up:

$$\int_c f(x,y,z) ds = \int_{c_1} f(x,y,z) ds_1 + \int_{c_2} f(x,y,z) ds_2 + \dots + \int_{c_n} f(x,y,z) ds_n.$$

Ex: Integrate $f(x,y,z) = x - 3y^2 + z$ over the line segments c_1 and c_2 . ($c_1 \cup c_2$)



$$\int_C f(x,y,z) ds = \int_{c_1} f(x,y,z) ds_1 + \int_{c_2} f(x,y,z) ds_2$$

$$c_1: \begin{cases} x=t & (0,0,0) \rightarrow (1,1,0) \\ y=t & t=0 \rightarrow t=1 \\ z=0 & (-\infty < t < \infty) \end{cases}$$

$$\begin{aligned} \vec{r}_1(t) &= x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k} \\ &= t\vec{i} + t\vec{j} + 0\vec{k} \\ \Rightarrow \frac{d\vec{r}_1}{dt} &= \vec{i} + \vec{j} \Rightarrow \left| \frac{d\vec{r}_1}{dt} \right| = \sqrt{1^2 + 1^2} = \sqrt{2} \end{aligned}$$

$$\Rightarrow ds_1 = \sqrt{2} dt$$

$$\int_{c_1} f(x(t), y(t), z(t)) ds_1 = \int_0^1 (t - 3t^2) \sqrt{2} dt$$

$$= \sqrt{2} \left(\frac{t^2}{2} - t^3 \right) \Big|_0^1 = -\frac{\sqrt{2}}{2}$$

$$c_2: \begin{cases} x=1 & (1,1,0) \rightarrow (1,1,1) \\ y=1 & t=0 \rightarrow t=1 \\ z=t & (-\infty < t < \infty) \end{cases}$$

$$\begin{aligned} \vec{r}_2(t) &= x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k} \\ &= \vec{i} + \vec{j} + t\vec{k} \\ \Rightarrow \frac{d\vec{r}_2}{dt} &= \vec{k} \Rightarrow \left| \frac{d\vec{r}_2}{dt} \right| = \sqrt{1^2} = 1 \end{aligned}$$

$$\Rightarrow ds_2 = dt$$

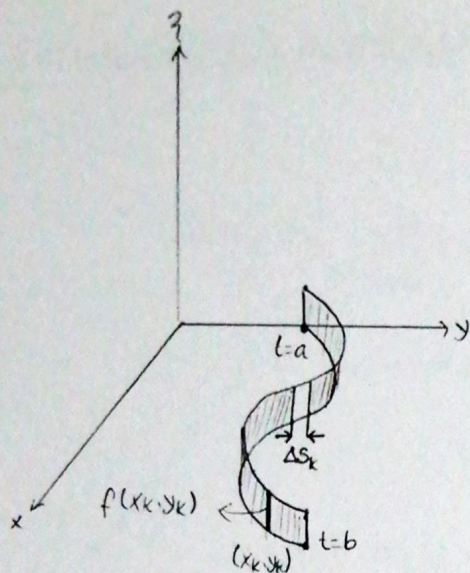
$$\int_{c_2} f(x(t), y(t), z(t)) ds_2 = \int_0^1 (-2 + t) dt$$

$$= \left(-2t + \frac{t^2}{2} \right) \Big|_0^1 = -\frac{3}{2}$$

$$\int_C f(x,y,z) ds = -\frac{\sqrt{2}}{2} + \left(-\frac{3}{2} \right) = \frac{-\sqrt{2}-3}{2}$$

Line Integrals in the Plane

Let C be a smooth curve in the plane and parametrized by $\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}$, $a < t < b$. We generate a cylindrical surface by moving a straight line along C orthogonal to the plane. If $z = f(x,y)$ is nonnegative continuous function over a region in the plane containing the curve C then the graph of f is a surface that lies above the plane.



$z = f(x, y) \geq 0$ from the definition.

$$\int_C f(x, y, z) ds = \lim_{\substack{n \rightarrow \infty \\ (\Delta S_k \rightarrow 0)}} \sum_{k=1}^n f(x_k, y_k, z_k) \Delta S_k$$

The line integral,

$$\int_C f(x, y, z) ds \text{ is the area of the "wall".}$$

Vector Fields and Line Integrals

Now, we turn our attention to the idea of a line integral of a vector field $\vec{F}$ along the curve C . Assume that the vector field,

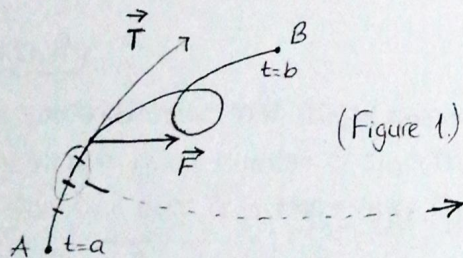
$$\vec{F}(x, y, z) = P(x, y, z)\vec{i} + Q(x, y, z)\vec{j} + R(x, y, z)\vec{k}$$

has continuous components, and that the curve C has a smooth parametrization,

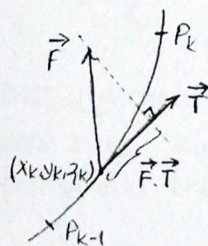
$$\vec{r}(t) = x(t)\vec{i} + y(t)\vec{j} + z(t)\vec{k}, \quad a \leq t \leq b.$$

The parametrization $\vec{r}(t)$ defines a forward direction along C . At each point along the path C , the tangent $\vec{T} = \frac{d\vec{r}}{ds}$ is a unit vector tangent to the path and pointing in this

forward direction. The line integral of the vector field is the line integral of the scalar tangential component of $\vec{F}$ along C .



(Figure 1)



The work done along the subarc shown here is approximately,

$$\vec{F}_k \cdot \vec{T}_k \Delta s_k, \text{ where } \vec{F}_k = \vec{F}(x_k, y_k, z_k) \text{ and } \vec{T}_k = \vec{T}(x_k, y_k, z_k)$$

The tangential component is given the dot product,

$$\vec{F} \cdot \vec{T} = \vec{F} \cdot \frac{d\vec{r}}{ds}$$