Asst. Prof. Kerem ALTUN

Personal Information

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International Researcher IDs

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Publons / Web Of Science ResearcherID: KIA-1625-2024

ScopusID: 23567569000 Yoksis Researcher ID: 178204

Education Information

Doctorate, Ihsan Dogramaci Bilkent University, Faculty of Engineering, Electrical and Electronics Engineering, Turkey 2005 - 2011

Postgraduate, Middle East Technical University, Faculty Of Engineering, Department Of Mechanical Engineering, Turkey 1999 - 2002

Undergraduate, Middle East Technical University, Faculty Of Engineering, Department Of Mechanical Engineering, Turkey 1995 - 1999

Research Areas

Artificial Intelligence, Computer Learning and Pattern Recognition, Motion Analysis, Electrical and Electronics Engineering, Sensing Devices and Transducers, System Dynamics and Control, Robotics, Mechatronics

Academic Titles / Tasks

Assistant Professor, Yildiz Technical University, Faculty Of Electrical & Electronics, Control And Automation Engineering, 2024 - Continues

Assistant Professor, Isik University, Mühendislik ve Doğa Bilimleri Fakültesi, Mechanical Engineering, 2022 - 2024
Assistant Professor, Izmir Institute Of Technology, Faculty of Engineering, Mechanical Engineering, 2020 - 2022
Assistant Professor, Isik University, Mühendislik ve Doğa Bilimleri Fakültesi, Makine Mühendisliği, 2016 - 2020
Researcher, The University of British Columbia, Faculty of Science, Computer Science, 2011 - 2012
Research Assistant, Ihsan Dogramaci Bilkent University, Elektrik ve Elektronik Mühendisliği, 2006 - 2011
Research Assistant, Middle East Technical University, Faculty Of Engineering, Department Of Mechanical Engineering, 1999 - 2005

Published journal articles indexed by SCI, SSCI, and AHCI

I. Recognizing affect in human touch of a robot

Altun K., MacLean K. E.

Pattern Recognition Letters, vol.66, pp.31-40, 2015 (SCI-Expanded)

II. Pedestrian dead reckoning employing simultaneous activity recognition cues

Altun K., Barshan B.

Measurement Science and Technology, vol.23, no.2, 2012 (SCI-Expanded)

III. Comparative study on classifying human activities with miniature inertial and magnetic sensors Altun K., Barshan B., Tunçel O.

Pattern Recognition, vol.43, no.10, pp.3605-3620, 2010 (SCI-Expanded)

IV. Representing and evaluating ultrasonic maps using active snake contours and Kohonen's selforganizing feature maps

Altun K., Barshan B.

Autonomous Robots, vol.29, no.2, pp.151-168, 2010 (SCI-Expanded)

V. Classifying human leg motions with uniaxial piezoelectric gyroscopes

Tunçel O., Altun K., Barshan B.

Sensors, vol.9, no.11, pp.8508-8546, 2009 (SCI-Expanded)

Books

I. Human activity recognition using inertial/magnetic sensor units

ALTUN K., BARSHAN ÖZAKTAŞ B.

in: Human Behavior Understanding, , Editor, Springer, pp.38-51, 2010

II. Performance evaluation of ultrasonic arc map processing techniques by active snake contours ALTUN K., BARSHAN ÖZAKTAŞ B.

in: European Robotics Symposium 2008 (Springer Tracts in Advanced Robotics (44)), , Editor, Springer, pp.185-194, 2008

Papers Published in Refereed Scientific Meetings

I. Experimental Evaluation of the Success of Peg-in-Hole Tasks Learned from Demonstration ARGÜZ S. H., ERTUĞRUL Ş., ALTUN K.

International Conference on Control, Decision and Information Technologies, İstanbul, Turkey, 17 May 2022, pp.861-866

II. Recognizing touch gestures for social human-robot interaction

Altuşlu T. B., Altun K.

ACM International Conference on Multimodal Interaction, ICMI 2015, Washington, United States Of America, 9 - 13 November 2015, pp.407-413

III. Real-time gait classification for persuasive smartphone apps: Structuring the literature and pushing the limits

Schneider O. S., MacLean K. E., Altun K., Karuei I., Wu M. M.

18th International Conference on Intelligent User Interfaces, IUI 2013, Santa Monica, CA, United States Of America, 19 - 22 March 2013, pp.161-172

IV. Employing active contours and artificial neural networks in representing ultrasonic range data ALTUN K., BARSHAN ÖZAKTAŞ B.

European Signal Processing Conference, Switzerland, 25 August 2008

V. Evaluation of egocentric navigation methods

Altun K., KOKU A. B.

14th IEEE Workshop on Robot and Human Interactive Communication, RO-MAN 2005, Nashville, TN, United States Of America, 13 - 15 August 2005, vol.2005, pp.396-401

VI. Systematic state equation derivation for linear systems using the normal tree method Altun K., PLATİN B. E., BALKAN R. T.

2003 ASME International Mechanical Engineering Congress, Washington, United States Of America, 15 - 21

Supported Projects

Altun K., Yücel H. S., TUBITAK Project, Measurement of Asymmetry in Jump and Volleyball Spike Movements Using Wearable Inertial Sensors, 2025 - 2027

Metrics

Publication: 13

Citation (Scopus): 652 H-Index (Scopus): 6