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Dissertations

Postgraduate, Development and application of flight control software based on STM32f4 microprocessor for quadrotor unmanned air vehicle, Yildiz Technical University, Faculty Of Mechanical Engineering, Department Of Mechatronics Engineering, 2022

Research Areas

Discrete Time Systems and Computer Control, Artificial Intelligence, Computer Learning and Pattern Recognition, System Dynamics and Control, Robotics

Academic Titles / Tasks

Research Assistant, Yildiz Technical University, Faculty Of Mechanical Engineering, Department Of Mechatronics Engineering, 2019 - Continues

Published journal articles indexed by SCI, SSCI, and AHCI

- I. Parameterizing history-dependent dynamics of skeletal muscle with a new nonlinear stiffness and damping formulation
 Gürkan B., Iscan M., Yılmaz C.
 TRANSACTIONS OF THE INSTITUTE OF MEASUREMENT AND CONTROL, vol.0, no.0, 2025 (SCI-Expanded)
- II. Adaptive elliptic trajectory-based received signal strength indicator antenna tracking algorithm Taş A. İ., Iscan M., Gurkan B., Yilmaz C.
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- III. A novel elliptic trajectory formula for active RSSI-based antenna tracking algorithm
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Papers Published in Refereed Scientific Meetings

 I. Sensor Fusion Design by Extended and Unscented Kalman Filter Approaches for Position and Attitude Estimation Pozisyon ve Yönelim Tahmini için, Genisletilmis ve Kokusuz Kalman Filtresi Yaklasimlariyla Sensör Füzyonu Tasarimi Sahin H., GÜRKAN B., ÖMÜRLÜ V. E. 4th International Congress on Human-Computer Interaction, Optimization and Robotic Applications, HORA 2022, Ankara, Turkey, 9 - 11 June 2022
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 III. STM32F407VG microprocessor based flight controller design experimented on a quadrotor ÖMÜRLÜ V. E., Gurkan B.
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Metrics

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