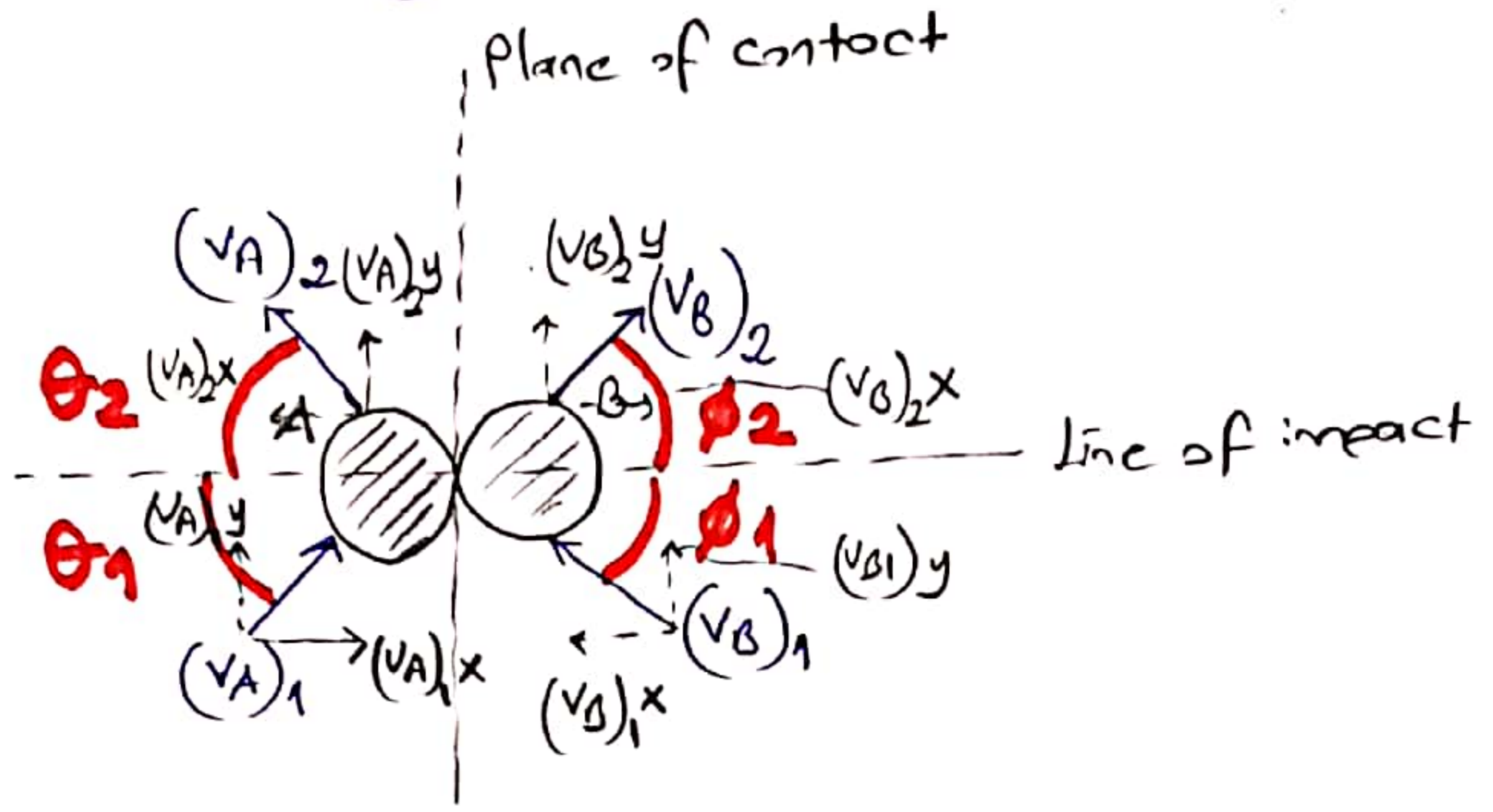


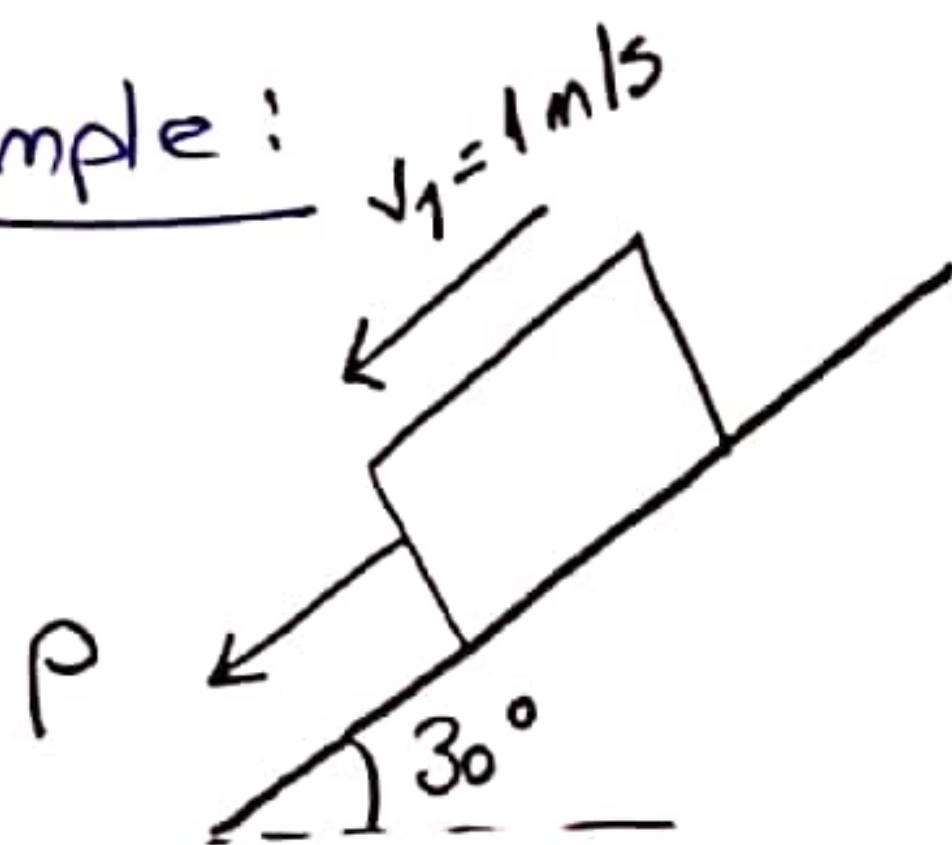
Oblique impact: When oblique impact occurs between two smooth particles, the particles move away from each other with velocities having unknown directions as well as unknown magnitudes.



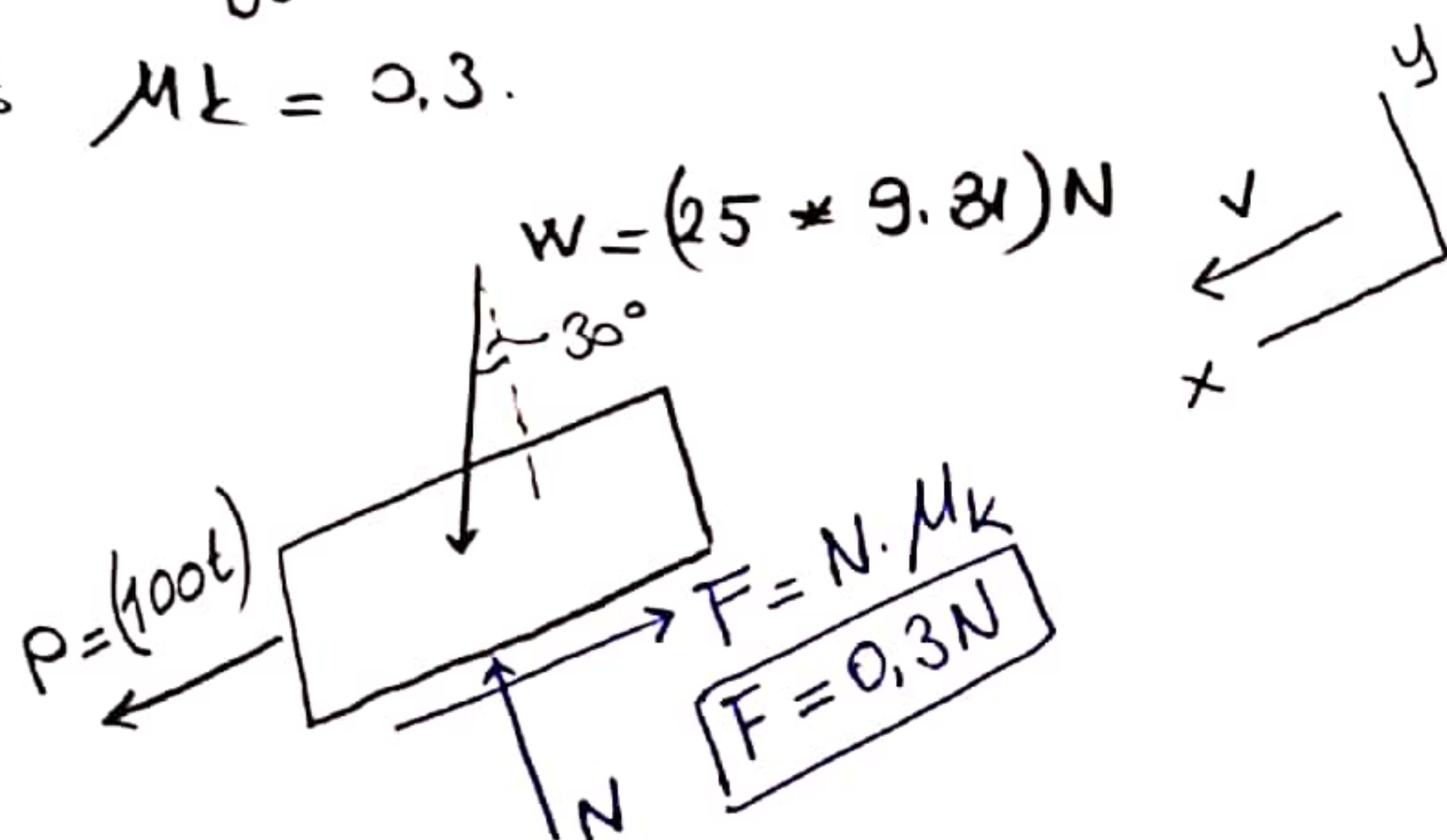
$$\begin{aligned}
 & m_A (v_{Ax})_1 \rightarrow \text{A} + \text{A} \xleftarrow{\int F \cdot dt} \text{A} \leftarrow \begin{matrix} m_A (v_{Ay})_2 \\ m_A (v_{Ax})_2 \end{matrix} \\
 & \quad \quad \quad \uparrow m_A (v_{Ay})_1 \\
 & m_B (v_{Bx})_1 \leftarrow \text{B} \xrightarrow{\int F \cdot dt} \text{B} = \text{B} \begin{matrix} \uparrow m_B (v_{By})_2 \\ \rightarrow m_B (v_{Bx})_2 \end{matrix} \\
 & \quad \quad \quad \uparrow m_B (v_{By})_1
 \end{aligned}$$

If the initial velocities are known, then 4 unknowns are present in the problem.

Example:



The 25 kg crate shown in Figure is acted upon by a force having a variable magnitude $P = (100t) \text{ N}$, where t is in seconds. Determine the crate's velocity 2 s after P has been applied. The initial velocity is $v_1 = 1 \text{ m/s}$ down the plane and the coefficient of kinetic friction between the crate and the plane is $\mu_k = 0.3$.



Principle of Impulse and momentum:

(+) Apply the principle of impulse and momentum in the x direction, we have

$$m(v_x)_1 + \sum \int_{t_1}^{t_2} F_x \cdot dt = m(v_x)_2$$

$$\underbrace{\begin{matrix} 25 & (1) \\ \text{kg} & \text{m/s} \end{matrix}} + \underbrace{\int_0^2 (100t) dt - 0.3N(2) + 25 \cdot 9.81 \cdot \sin 30(2)}_{\text{Impulse}}$$

$$= 25(v_2)$$

$$\boxed{25 + 200 - 0.6N + 245.25 = 25v_2} \quad \text{--- (A)}$$

In the y direction, the equation of equilibrium can be applied:

$$\uparrow \sum F_y = 0$$

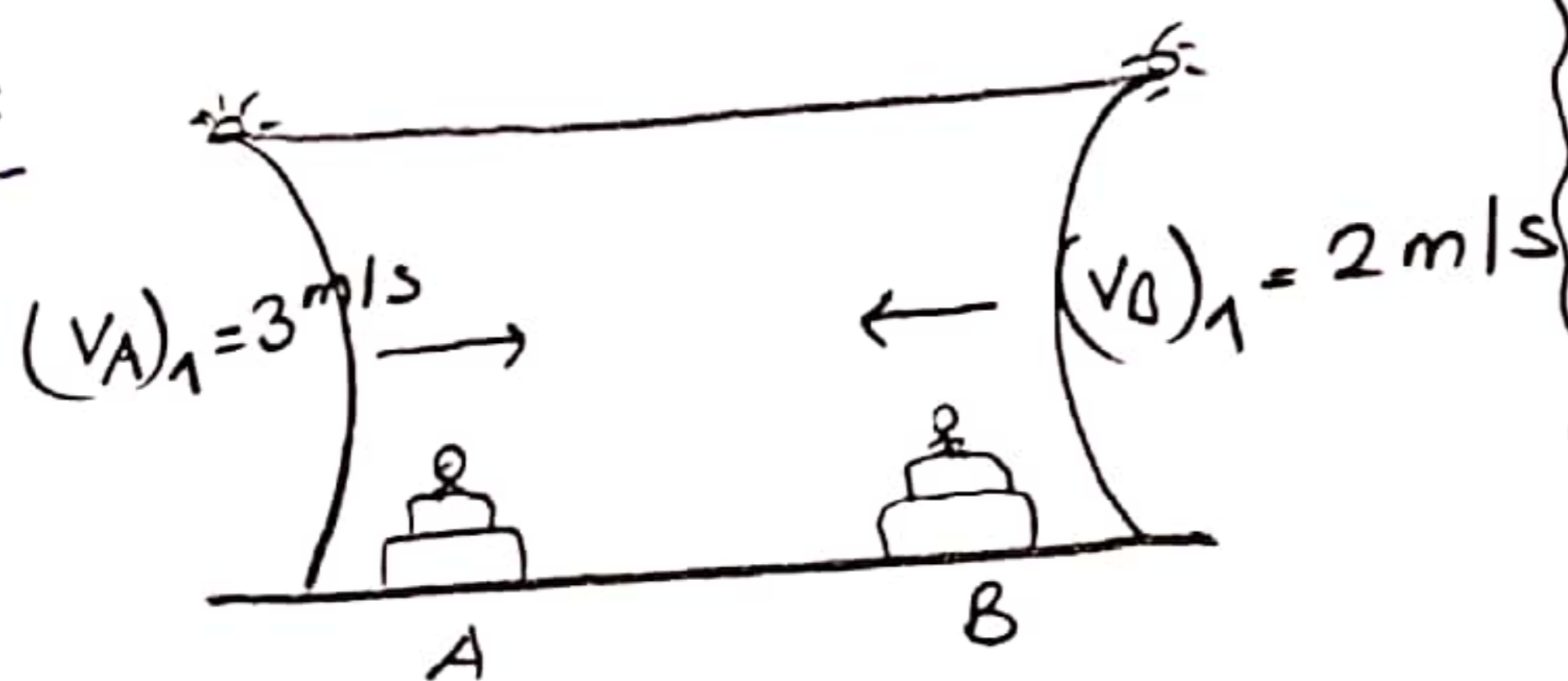
$$-25 \cdot 9.81 \cdot \cos 30 + N = 0$$

$$N = 212,39 \text{ N} \quad \dots \textcircled{B}$$

Let's substitute \textcircled{B} into \textcircled{A} ;

$$V_2 = 13,7 \text{ m/s}$$

Example:



The bumper cars A and B in Figure each have a mass of 150 kg and are coasting with the velocities shown before they freely collide head on. If no energy is lost during the collision, determine their velocities after collision.

** When particles collide or interact, conservation of linear momentum is often applied.

Conservation of momentum:

$$(\rightarrow) m_A (V_A)_1 + m_B (V_B)_1 = m_A (V_A)_2 + m_B (V_B)_2$$

$$\underbrace{150}_{\text{kg}} \underbrace{(3)}_{\text{m/s}} + \underbrace{150}_{\text{kg}} \underbrace{(-2)}_{\text{m/s}} = \underbrace{150}_{\text{kg}} (V_A)_2 + \underbrace{150}_{\text{kg}} (V_B)_2$$

$$(V_A)_2 = 1 - (V_B)_2 \quad \dots \textcircled{1}$$

Since no energy is lost, the conservation of energy theorem can be applied as follows:

$$T_1 + V_1 = T_2 + V_2$$

$$\frac{1}{2} m_A (v_A)_1^2 + \frac{1}{2} m_B (v_B)_1^2 + 0 = \frac{1}{2} m_A (v_A)_2^2 + \frac{1}{2} m_B (v_B)_2^2$$

$\frac{1}{2} m_A (v_A)_1^2$ is 150 kg
 $\frac{1}{2} m_B (v_B)_1^2$ is T_1 and 150 kg
 $(3 \text{ m/s})^2$
 $(2 \text{ m/s})^2$

$\frac{1}{2} m_A (v_A)_2^2$ is 150 kg
 $\frac{1}{2} m_B (v_B)_2^2$ is T_2 and 150 kg
 $+ 0$ is V_2

$$(v_A)_2^2 + (v_B)_2^2 = 13 \quad \text{--- (2)}$$

Let's substitute Eq (1) into (2) and simplify:

$$(v_B)_2^2 - (v_B)_2 - 6 = 0$$

two roots:

$$\begin{cases} (v_B)_2 = 3 \text{ m/s} \\ (v_B)_2 = -2 \text{ m/s} \end{cases} \Rightarrow \text{the velocity of B just before the collision}$$

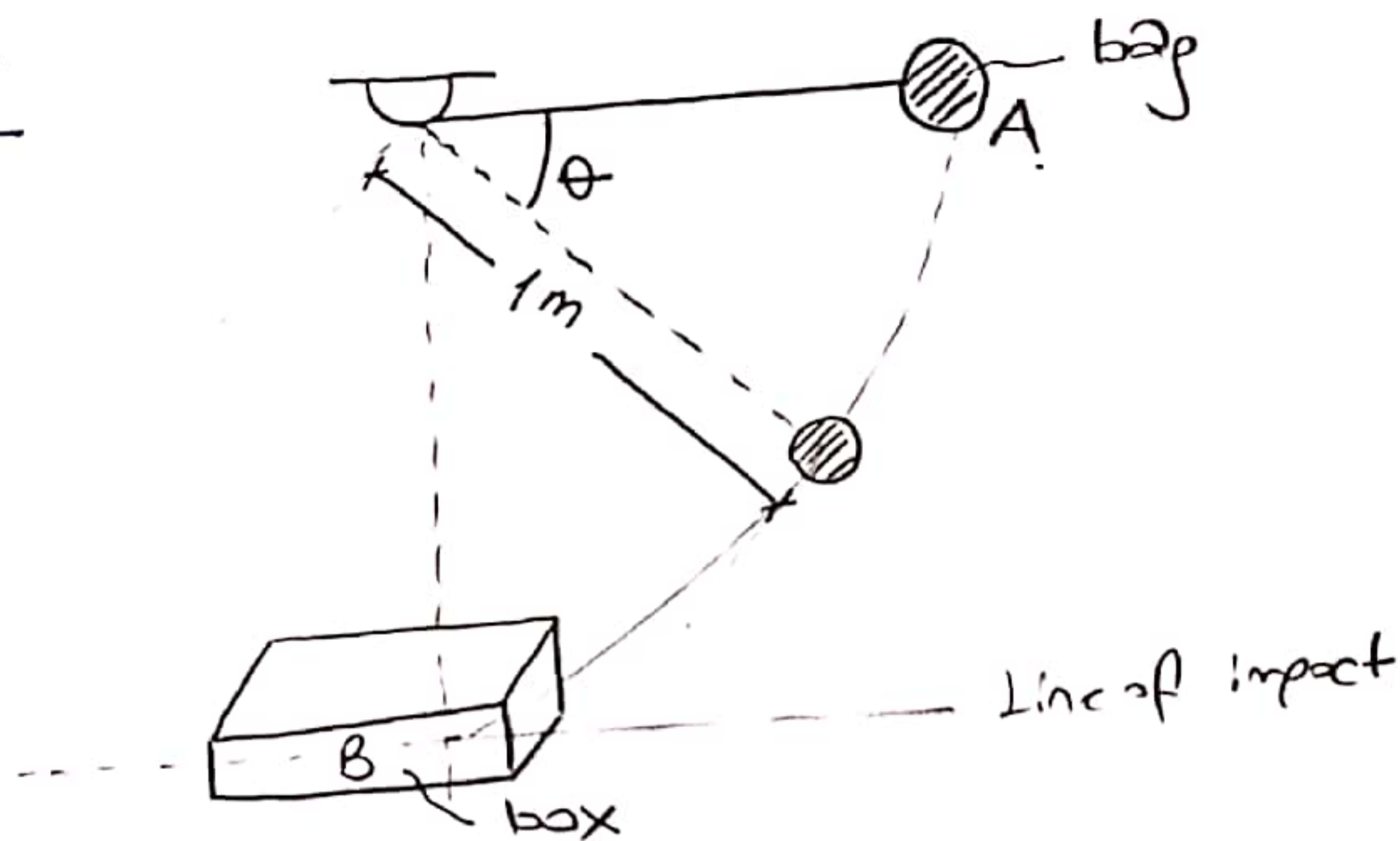
it must be the velocity of B just after collision

$$(v_B)_2 = 3 \text{ m/s} \rightarrow$$

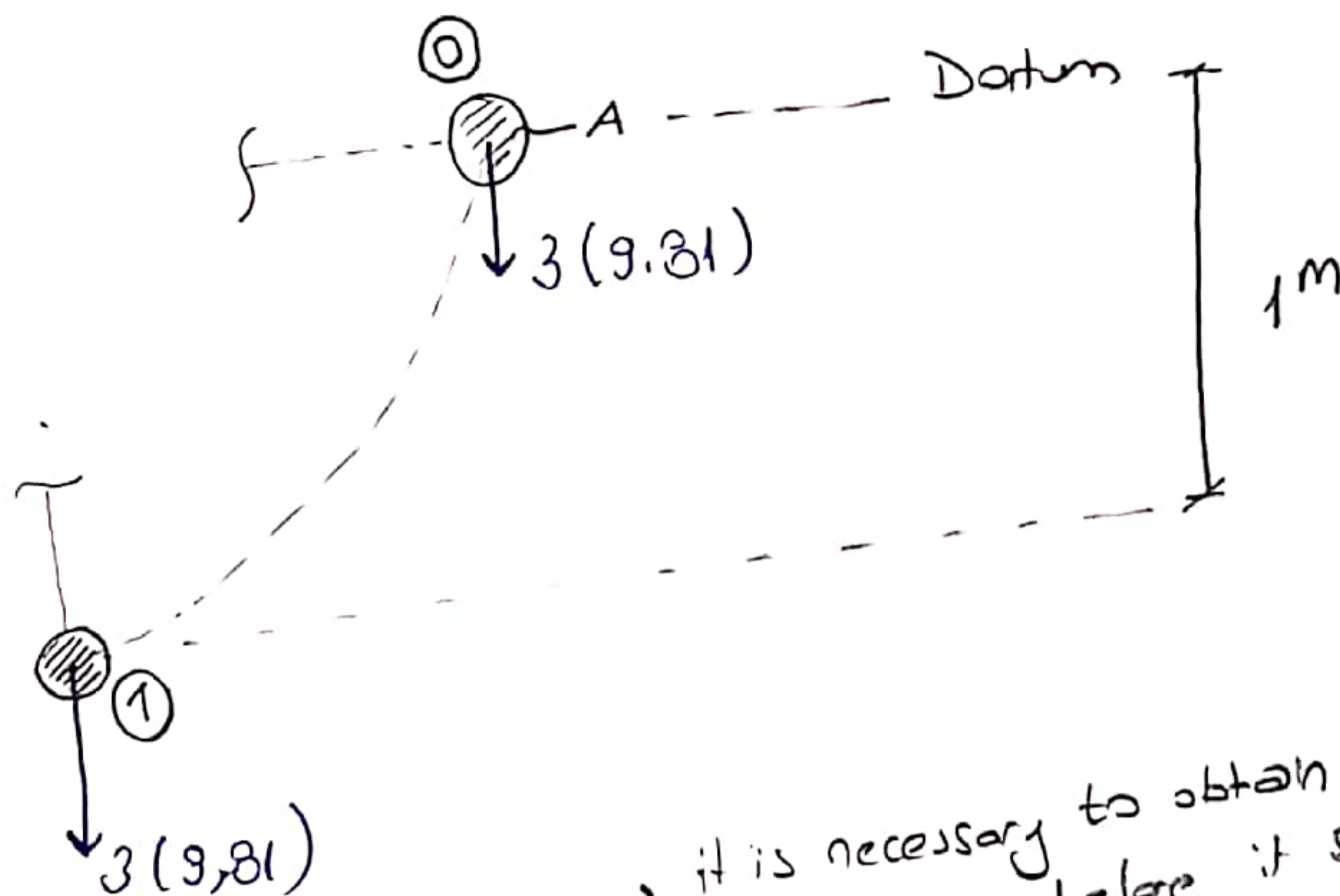
Substituting this result into Eq (1);

$$(v_A)_2 = 1 - 3 = -2 \text{ m/s} = 2 \text{ m/s} \leftarrow$$

Example:



The bag A, having a mass of 3 kg, is released from rest at the position $\theta = 0^\circ$, as shown in figure. After falling to $\theta = 90^\circ$, it strikes an 9 kg box B. If the coefficient of restitution between the bag and box is $e = 0.5$, determine the velocities of the bag and box just after impact. What is the loss of energy during collision?



Conservation of energy:

it is necessary to obtain the velocity of the bag just before it strikes to box.

$$T_0 + V_0 = T_1 + V_1$$

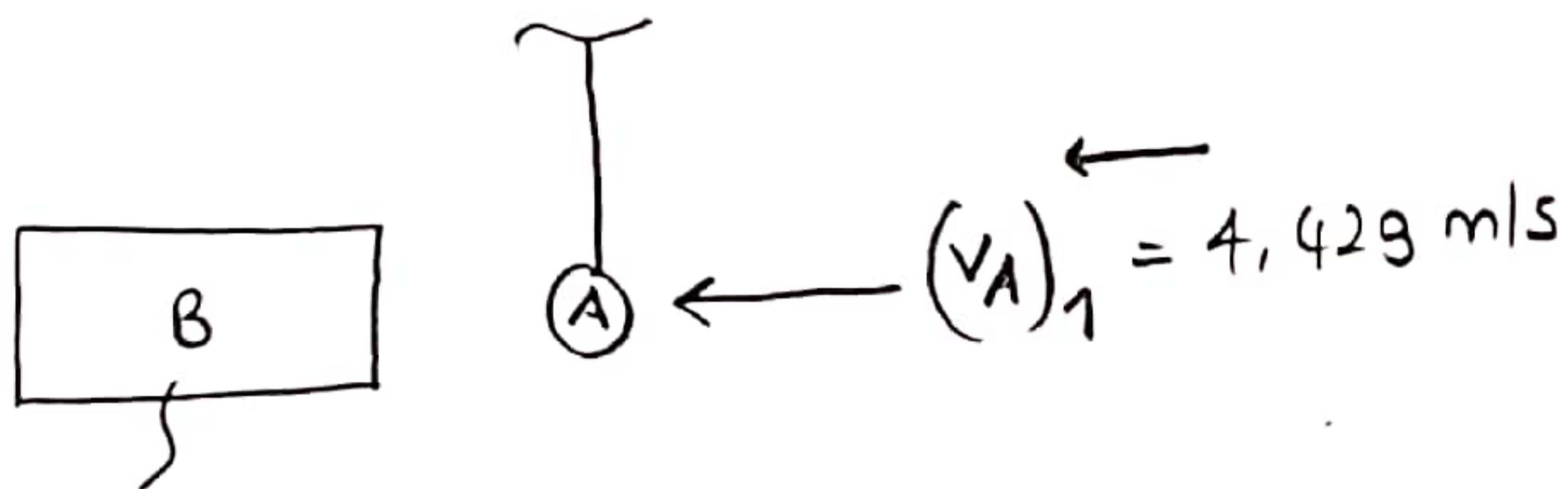
$$\underbrace{0}_{\text{at datum}} + \underbrace{0}_{\text{at datum}} = \frac{1}{2} (3) (v_A)_1^2 - \underbrace{3 \cdot 9.81 \cdot (1)}_{mgh}$$

$$(v_A)_1 = 4.429 \text{ m/s}$$

① represents the datum $\Rightarrow \theta = 0^\circ$

Conservation of momentum: Applying the conservation of momentum to the system;

$$\overset{+}{\leftarrow} m_B (v_B)_1 + m_A (v_A)_1 = m_B (v_B)_2 + m_A (v_A)_2$$



$$(v_B)_1 = 0$$

Just before impact.

$$0 + 3(4.429) = 3(v_B)_2 + 3(v_A)_2$$

$$(v_A)_2 = 4.429 - (v_B)_2 \quad \text{--- (1)}$$

Coefficient of Restitution:

$$\overset{+}{\leftarrow} e = \frac{(v_B)_2 - (v_A)_2}{(v_A)_1 - (v_B)_1}$$

$$0.5 = \frac{(v_B)_2 - (v_A)_2}{4.429 - 0}$$

$$(v_A)_2 = (v_B)_2 - 2.2145 \quad \text{--- (2)}$$

Solving Eqs (1) and (2);

$$(v_A)_2 = -0.554 \text{ m/s} = 0.554 \text{ m/s} \rightarrow$$

$$(v_B)_2 = 1.66 \text{ m/s} \leftarrow$$

Loss of Energy: Applying the principle of work and energy to the bag and box just before and just after collision;

$$\sum U_{1 \rightarrow 2} = T_2 - T_1$$

$$\sum U_{1 \rightarrow 2} = \left[\frac{1}{2} 9 (1.661)^2 + \frac{1}{2} 3 (0.554)^2 \right]$$

T_2

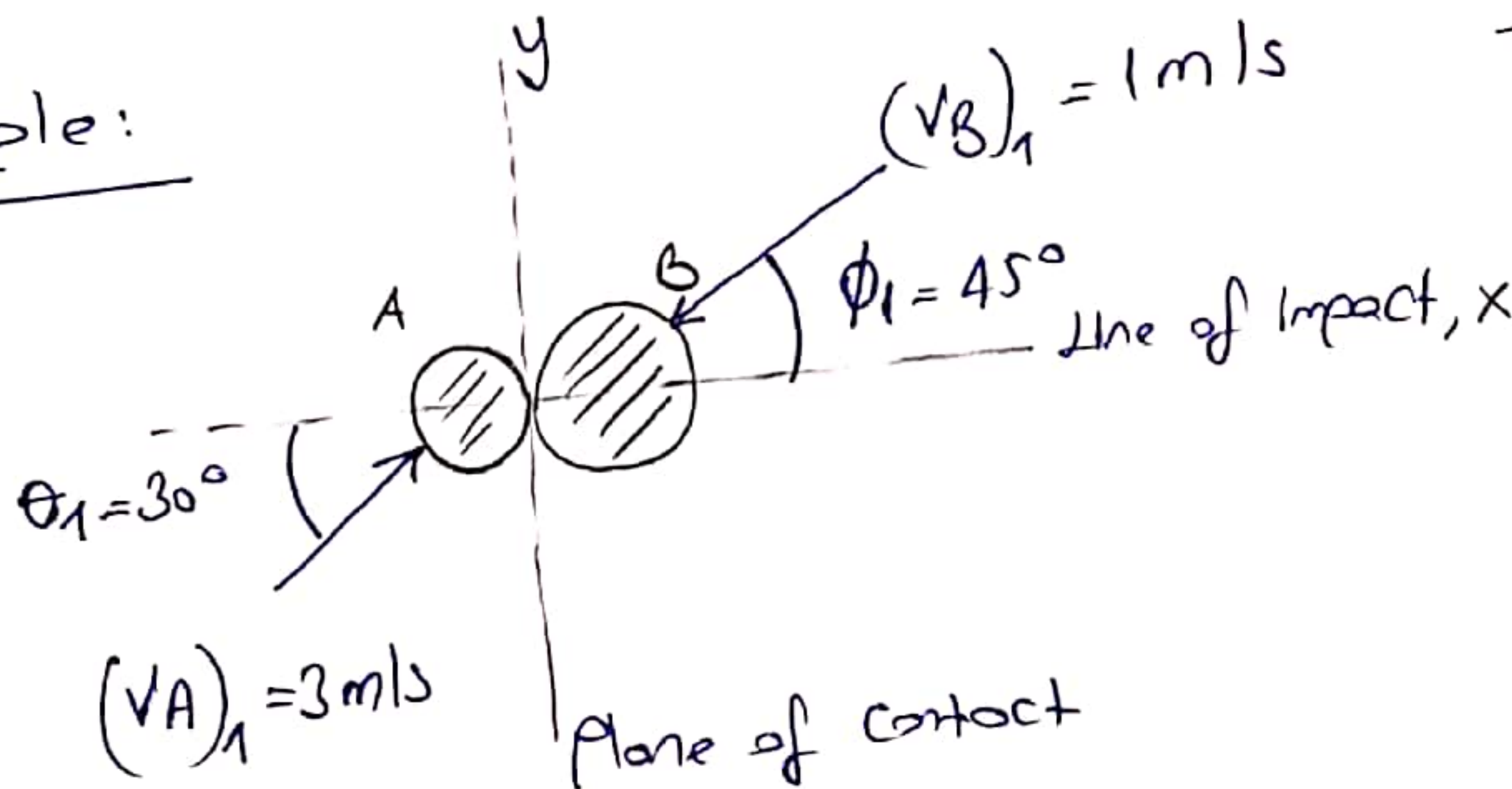
$$- \left[\frac{1}{2} 3 (4.429)^2 \right]$$

T_1

$$\sum U_{1 \rightarrow 2} = -16.6 \text{ J}$$

the energy loss occurs due to inelastic deformation during the collision.

Example:



Two smooth disks (A) and (B), having a mass of 1 kg and 2 kg, respectively collide with the velocities shown in Figure. If the coefficient of restitution for the disks is

$e = 0.75$, determine the x and y components of the final velocity of each disk just after collision.

$$(V_{Ax})_1 = 3 \cdot \cos 30 = 2.598 \text{ m/s}$$

$$(V_{Ay})_1 = 3 \cdot \sin 30 = 1.5 \text{ m/s}$$

$$(V_{Bx})_1 = -1 \cdot \cos 45 = -0.7071 \text{ m/s}$$

$$(V_{By})_1 = -1 \cdot \sin 45 = -0.7071 \text{ m/s}$$

x and y components of initial velocities of A and B disks.

Let's assume that: 4 unknown velocity components after collision are act in the positive directions.

$$m_A (V_{Ax})_1 + \left(\text{Disk A} \xleftarrow{-\int F \cdot dt} \right) = \left(\text{Disk A} \xrightarrow{m_A (V_{Ax})_2} \uparrow m_A (V_{Ay})_2 \right)$$

$$\left(\text{Disk B} \xleftarrow{m_B (V_{By})_1} \right) + \left(\text{Disk B} \xrightarrow{\int F \cdot dt} \right) = \left(\text{Disk B} \xrightarrow{m_B (V_{Bx})_2} \uparrow m_B (V_{By})_2 \right)$$

Conservation of momentum in x direction:

$$\begin{aligned}
 (+ \rightarrow) \quad & \underbrace{m_A (V_{Ax})_1}_{1 \text{ kg}} + \underbrace{m_B (V_{Bx})_1}_{2 \text{ kg}} = \underbrace{m_A (V_{Ax})_2}_{1 \text{ kg}} + \underbrace{m_B (V_{Bx})_2}_{2 \text{ kg}} \\
 & \quad \quad \quad (2.598 \text{ m/s}) \quad \quad \quad (-0.7071 \text{ m/s}) \\
 & \quad \quad \quad = 1 (V_{Ax})_2 + 2 (V_{Bx})_2
 \end{aligned}$$

$$(V_{Ax})_2 + 2 (V_{Bx})_2 = 1.184 \quad \dots \text{Eq (1)}$$

$$(\rightarrow) e = \frac{(v_{BX})_2 - (v_{AX})_2}{(v_{AX})_1 - (v_{BX})_1}$$

$$0,75 = \frac{(v_{BX})_2 - (v_{AX})_2}{2,598 - (-0,7071)}$$

$$(v_{BX})_2 - (v_{AX})_2 = 2,482 \dots \text{Eq (2)}$$

Solve Eq (1) and Eq (2);

$$(v_{AX})_2 = -1,26 \text{ m/s} \leftarrow 1,26 \text{ m/s}$$

$$(v_{BX})_2 = 1,22 \text{ m/s} \rightarrow$$

Conservation of momentum of each disk in y direction;

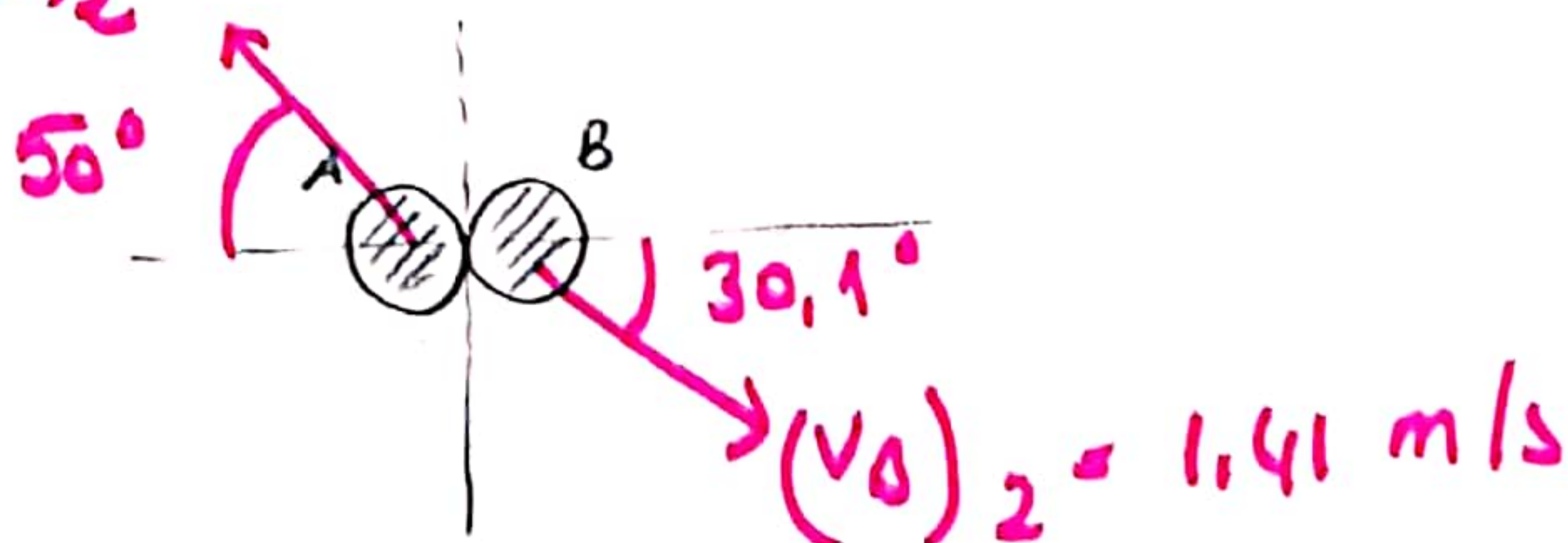
$$(\uparrow) m_A (v_{Ay})_1 = m_A (v_{Ay})_2$$

$$(v_{Ay})_2 = 1,50 \text{ m/s} \uparrow$$

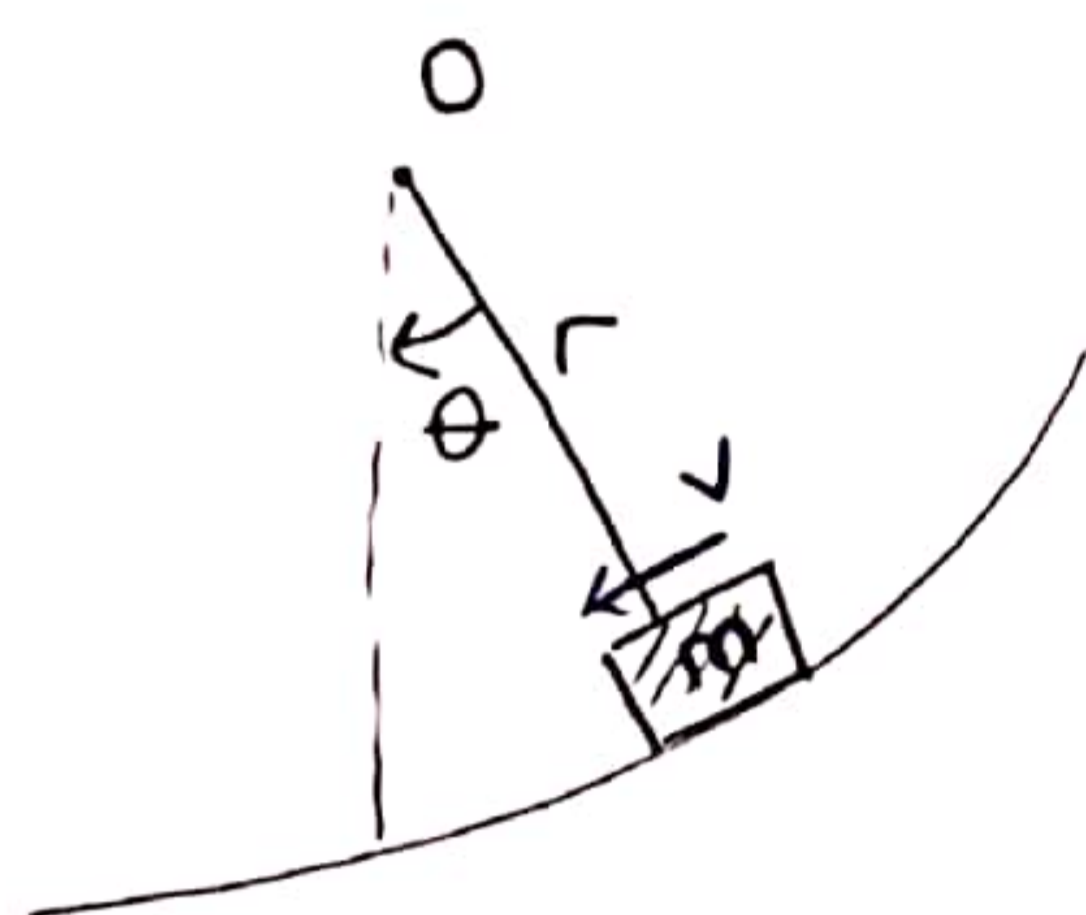
$$(\uparrow) m_B (v_{By})_1 = m_B (v_{By})_2$$

$$(v_{By})_2 = -0,777 \text{ m/s} = 0,777 \text{ m/s} \downarrow$$

$$(v_A)_2 = 1,96 \text{ m/s}$$



Example: The box shown in Figure has a mass "m" and travels down the smooth circular ramp such that when it is at the angle θ it has a speed v . Determine its angular momentum about point "O" at this instant and the rate of increase in its speed.

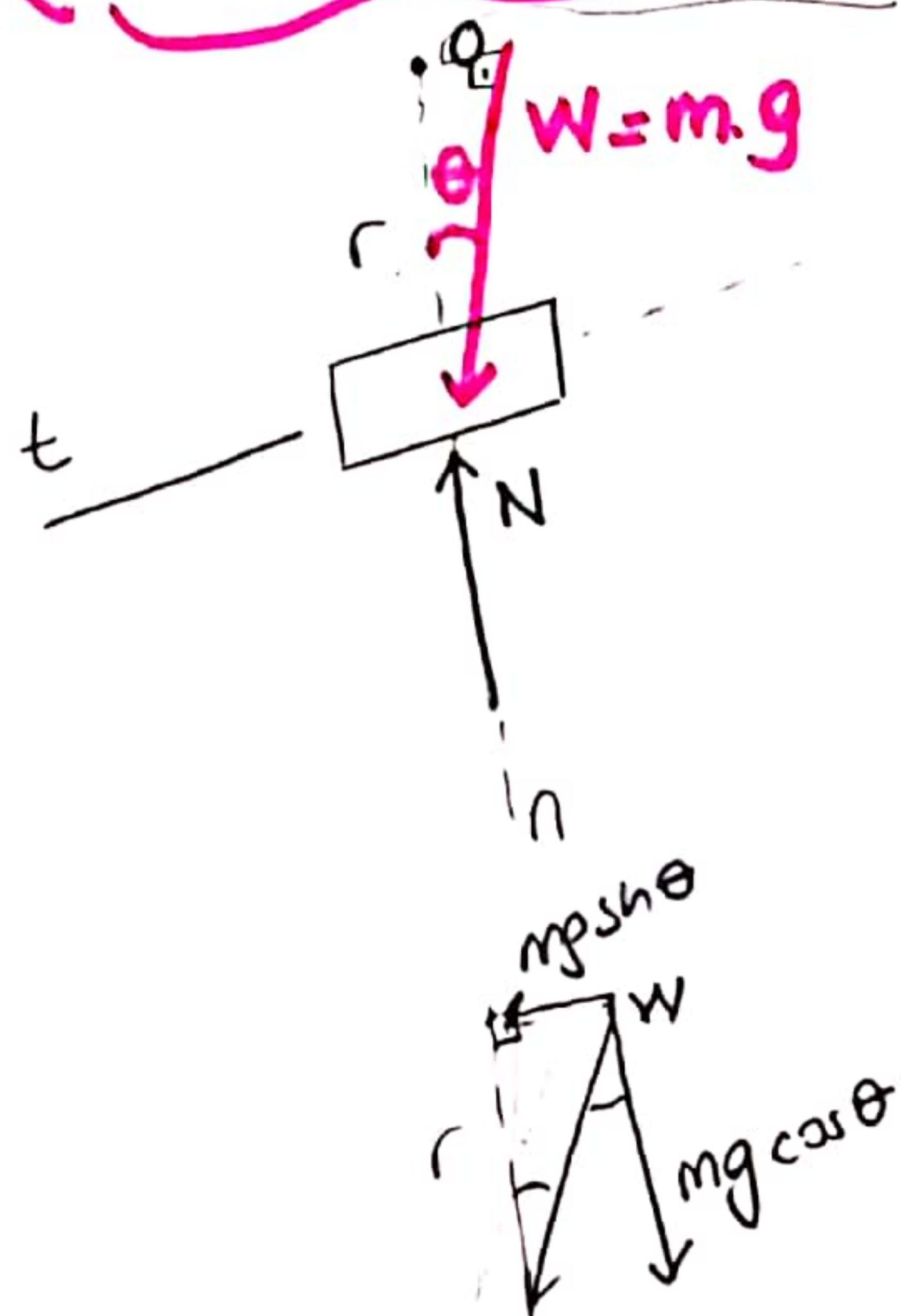


The angular momentum is ;

$$H_O = r \underbrace{mv}_{\text{linear momentum}}$$

The rate of increase in its speed ($\frac{dv}{dt} = a$) can be found by applying ;

$$+\uparrow \sum M_O = \dot{H}_O$$



Only the weight $W = mg$ contributes a moment about point "O".

$$+\uparrow \sum M_O = \dot{H}_O$$

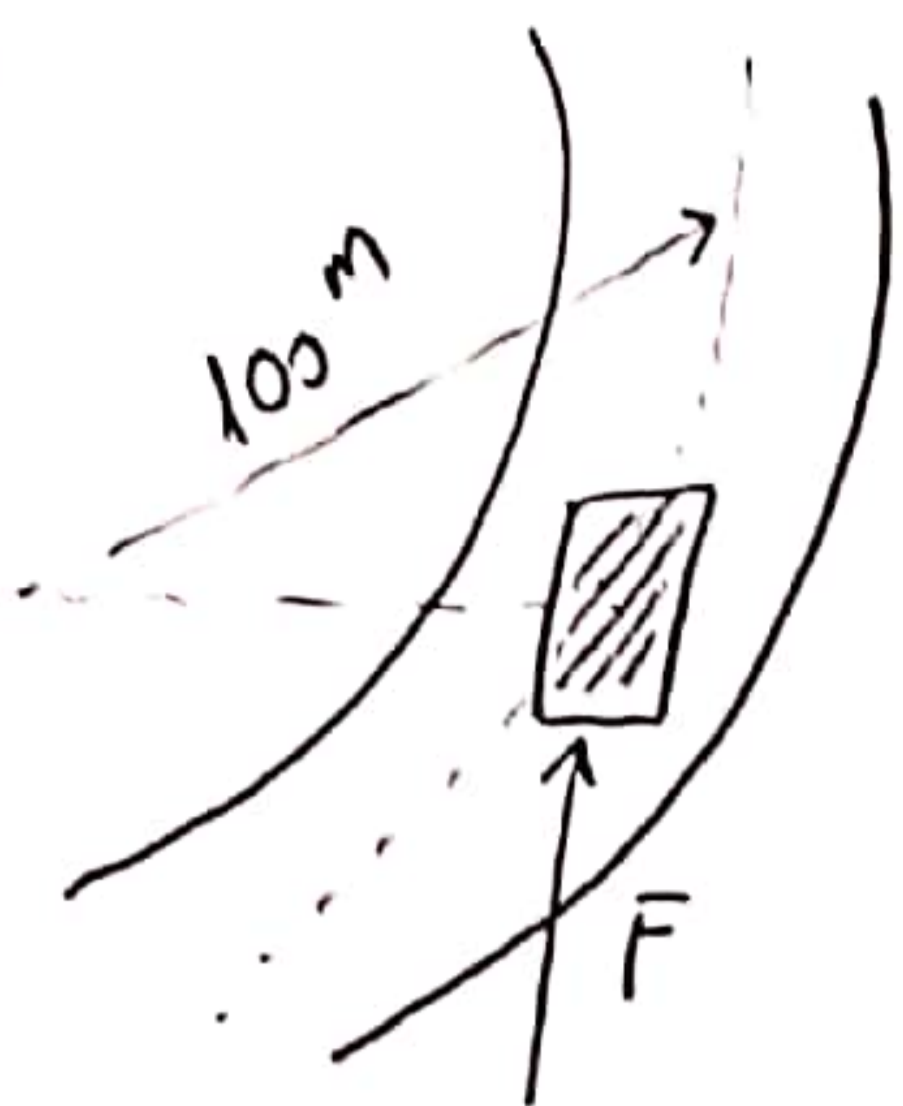
$$mg (r \sin \theta) = \frac{d}{dt} (r \cdot m \cdot v)$$

r and m are constant ;

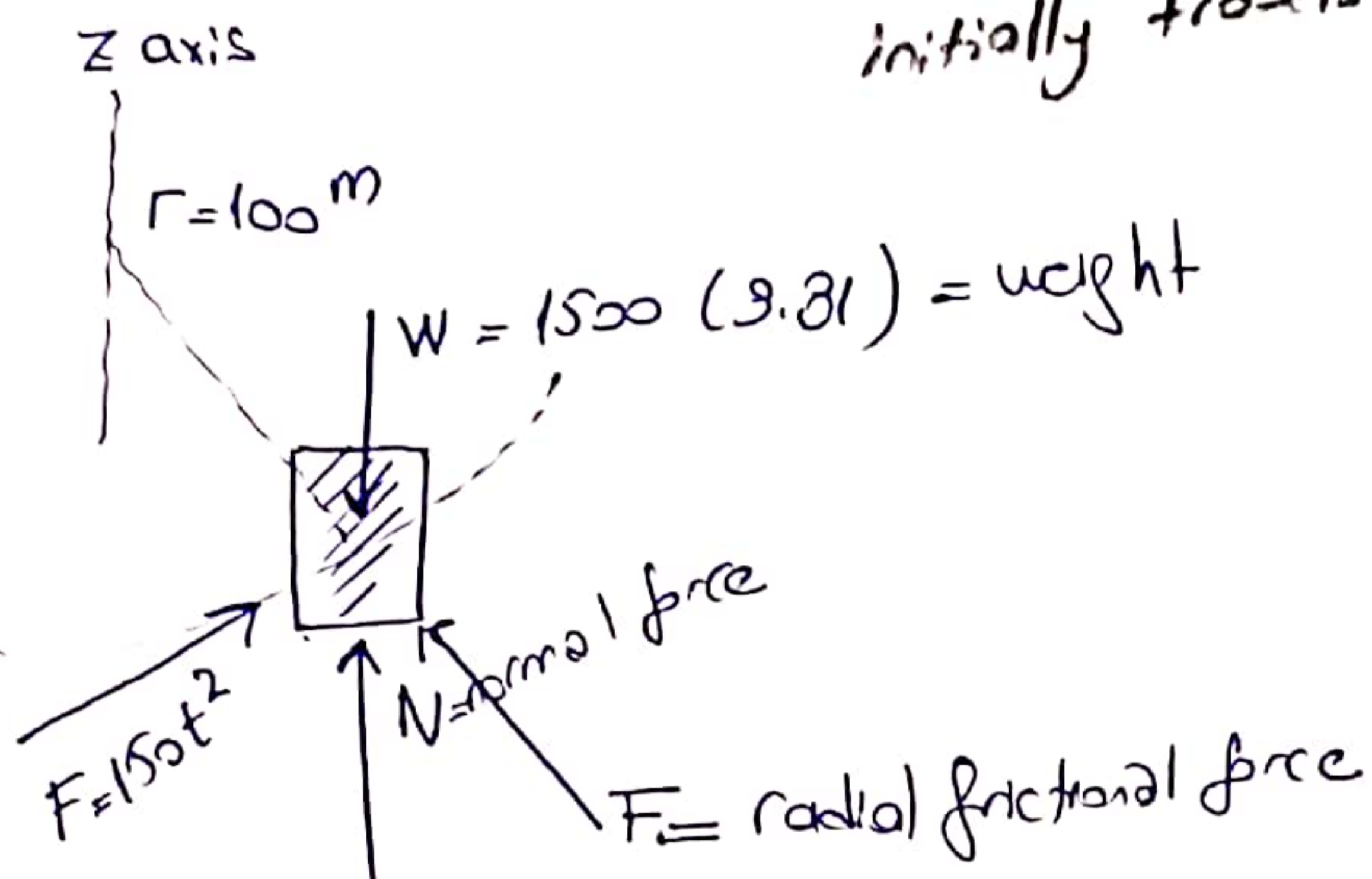
$$mg \cancel{r} \sin \theta = \cancel{r} m \frac{dv}{dt}$$

$$\frac{dv}{dt} = g \sin \theta$$

Example:



The 1500 kg car travels along the circular road shown in Figure. If the traction force of the wheels on the road is $F = (150t^2) \text{ N}$, where t is in seconds, determine the speed of the car when $t = 5 \text{ s}$. The car initially travels with a speed of 5 m/s.



W, N

N , W and F will be eliminated since they act parallel to the Z axis or pass through it. Let's ~~apply~~ the principle of angular impulse and momentum about the " Z " axis;

Principle of Angular impulse and momentum

$$\begin{aligned}
 (H_Z)_1 + \sum \int_{t_1}^{t_2} (M_Z) \cdot dt &= (H_Z)_2 \\
 \underbrace{100\text{m}}_{r} \cdot \underbrace{1500\text{kg}}_m \underbrace{5\text{ m/s}}_{(v)_1} + \int_0^5 (150t^2) (\underbrace{100\text{m}}_r) dt &= \underbrace{100\text{m}}_r \cdot \underbrace{1500\text{kg}}_m \underbrace{(v)_2}_{?} \\
 \boxed{(v)_2 = 9.17 \text{ m/s}}
 \end{aligned}$$