

Volterra Yöntemi

$$u(x) = f(x) + \int_a^b K(x,t) u(t) dt \quad (1)$$

$$u(t) = f(t) + \int_a^b K(t,y) u(y) dy$$

$K(x,t)$ nin karşı fonk. nu $K(x,t)$ olmak üzere

$$\int_a^b K(x,t) u(t) dt = \int_a^b K(x,t) f(t) dt + \int_a^b \left(\int_a^b \underbrace{K(x,t) K(t,y)} u(y) dy \right) dt$$

$$\int_a^b K(x,t) u(t) dt = \int_a^b K(x,t) f(t) dt + \int_a^b [K(x,y) + K(x,y)] u(y) dy$$

$$\cancel{\int_a^b K(x,t) u(t) dt} = \int_a^b K(x,t) f(t) dt + \cancel{\int_a^b K(x,y) u(y) dy} + \int_a^b K(x,y) u(y) dy$$

$$\int_a^b K(x,t) f(t) dt + \int_a^b K(x,t) u(t) dt = 0$$

$$\int_a^b K(x,t) u(t) dt = - \int_a^b K(x,t) f(t) dt$$

① de yerine koyarsak

$$u(x) = f(x) - \int_a^b K(x,t) f(t) dt$$

Volterra yönt. ancak $\lambda=1$ için denklemin
çözümü söz konusu olacağından

$$\Gamma(x, t; \lambda) = \Gamma(x, t; 1)$$

$$\Gamma(x, t; 1) = \sum_{n=1}^{\infty} K_{(n)}(x, t) = -k(x, t)$$

$$u(x) = f(x) + \int_a^b \Gamma(x, t; 1) f(t) dt$$

$$u(x) = f(x) + \int_a^b [-k(x, t)] f(t) dt$$

Örnekle $u(x) = x + \int_0^1 x t u(t) dt$ Volterra yönt.

$$K_{(1)}(x, t) = x t$$

$$K_{(2)}(x, t) = \int_0^1 K(x, y) K_{(1)}(y, t) dy = \int_0^1 x y y t dy = \frac{x t}{3}$$

$$K_{(3)}(x, t) = \int_0^1 K(x, y) K_{(2)}(y, t) dy = \int_0^1 x y \frac{y t}{3} dy = \frac{x t}{3^2}$$

⋮

$$K_{(n)}(x, t) = \frac{x t}{3^{n-1}}$$

$$- K(x, t) = \sum_{n=1}^{\infty} K_{(n)}(x, t) \quad u(x) = f(x) - \int_a^b K(x, t) f(t) dt$$

$$= xt \left[1 + \frac{1}{3} + \frac{1}{3^2} + \dots \right]$$

$$r = \frac{1}{3} < 1$$

geometric series

$$= xt \frac{1}{1 - \frac{1}{3}} = \frac{3xt}{2}$$

$f(t)$

↓

$$u(x) = x + \int_0^1 xt u(t) dt = x + \int_0^1 \frac{3}{2} xt t dt$$

$$= \frac{3x}{2} \checkmark$$

Volterra İntegral Denklemleri

$u(x)$ bilinmeyen fonk. $K(x,t)$ sekonder fonk
 λ parametre

$$\phi(x) = \lambda \int_a^x K(x,t) u(t) dt \quad \text{1. cins Volterra}$$

$$u(x) = f(x) + \lambda \int_a^x K(x,t) u(t) dt \quad \text{2. cins Volterra}$$

$$f(x) = 0$$

$$u(x) = \lambda \int_a^x K(x,t) u(t) dt \quad \text{2. cins homojen Volterra}$$

Dif. Denklemlere dönüştürerek Çözümü:

$$f(x) = \int_{a(x)}^{b(x)} F(x,t) dt$$

$$f'(x) = \int_{a(x)}^{b(x)} \frac{\partial}{\partial x} [F(x,t)] dt + \frac{db}{dx} (F(x,b(x))) - \frac{da}{dx} (F(x,a(x)))$$

Örnek

$$2x^3 = \int_0^x \left[1 - 5(x-t) + 2(x-t)^2 \right] u(t) dt$$

$$* \quad 6x^2 = \int_0^x (-5 + 4(x-t)) u(t) dt + u(x)$$

$$* 12x = \int^x 4u(t) dt - 5u(x) + u'(x)$$

⑥

$$12 = 4u(x) - 5u'(x) + u''(x)$$

$$u''(x) - 5u'(x) + 4u(x) = 12$$

2. mertebeden sabit katsayılı lineer dif denk.

$$\left. \begin{array}{l} u(0) = 0 \\ u'(0) = 0 \end{array} \right\} \text{bulunacak!}$$

$$u(x) = C_1 e^x + C_2 e^{4x} + 3$$

$$x=0 \quad \left. \begin{array}{l} u=0 \\ u'=0 \end{array} \right\} \quad u'(x) = C_1 e^x + 4C_2 e^{4x}$$

$$C_2 = 1 \quad C_1 = -4$$

$$\boxed{u(x) = -4e^x + e^{4x} + 3}$$

$$C_1 + C_2 + 3 = 0$$

$$\begin{array}{rcl} \cancel{C_1} + C_2 & = & -3 \\ -\cancel{C_1} + 4C_2 & = & 0 \\ \hline -3C_2 & = & -3 \end{array}$$

Çözümü kullanarak Yardımıyla Çözüm:

$$u(x) = f(x) + \lambda \int_0^x K(x,t) u(t) dt \quad 2. \text{ cins Volterra}$$

Bu denklemin $u(x) = \sum_{n=0}^{\infty} \lambda^n u_n(x) = u_0(x) + \lambda u_1(x) + \lambda^2 u_2(x) + \dots$ (2)

Şeklinde çözümü yazılacaktır.

$$u_0(x) + \lambda u_1(x) + \lambda^2 u_2(x) + \dots = f(x) + \lambda \int_0^x K(x,t) [u_0(t) + \lambda u_1(t) + \lambda^2 u_2(t) + \dots] dt$$

$$u_0(x) = f(x)$$

$$u_1(x) = \int_0^x K(x,t) \underbrace{u_0(t)}_{f(t)} dt$$

$$u_2(x) = \int_0^x K(x,t) u_1(t) dt$$

$\vdots$

Böylece $\begin{cases} u_0(x) = f(x) \end{cases}$

$$\begin{cases} u_n(x) = \int_0^x K(x,t) u_{n-1}(t) dt \quad (n \geq 1) \end{cases}$$

$u(x) = \sum_{n=0}^{\infty} \lambda^n u_n(x)$ serinin yakınsaklığı ile sonucu ulaşılır.

İterasyon Tekniği

$K_{(n)}(x,t) = K(x,t)$ olmak üzere

$$K_{(n)}(x,t) = \int_t^x K(x,y) K_{(n-1)}(y,t) dy$$

$$K_{(n)}(x,t) \quad u_2(x)$$

$$u_n(x) = \int_0^x K_{(n)}(x,t) f(t) dt$$

Burada (2) denklemini yeniden düzenlersek

$$u(x) = f(x) + \sum_{i=1}^{\infty} \lambda^i \int_0^x K_{(i)}(x,t) f(t) dt \text{ bulunur.}$$

$K(x,t)$ sürekli fonksiyon olduğundan

$$\sum_{i=1}^{\infty} \lambda^{i-1} K_{(i)}(x,t) \text{ mutlak ve düzgün yak. olup}$$

Rezolvent dir.

$$R(x,t;\lambda) = \sum_{i=1}^{\infty} \lambda^{i-1} K_{(i)}(x,t)$$

$$u(x) = f(x) + \lambda \int_0^x R(x,t;\lambda) f(t) dt$$

ile köşme ulaşılır. 0

Örnek

$$u(x) = x + \int_0^x u(t) dt$$

$$K_{(1)}(x, t) = K(x, t) = 1$$

$$K_{(2)}(x, t) = \int_t^x K(x, y) K_{(1)}(y, t) dy = \int_t^x 1 \cdot 1 dy = x - t$$

$$K_{(3)}(x, t) = \int_t^x K(x, y) K_{(2)}(y, t) dy = \int_t^x 1 \cdot (y - t) dy = \frac{(x - t)^2}{2}$$

$$K_{(4)}(x, t) = \int_t^x K(x, y) K_{(3)}(y, t) dy = \int_t^x 1 \cdot \frac{(y - t)^2}{2} dy = \frac{(x - t)^3}{3 \cdot 2}$$

$$\vdots$$

$$K_{(n)}(x, t) = \frac{(x - t)^{n-1}}{(n-1)!}$$

$$R(x, t; \lambda) = \sum_{n=1}^{\infty} \lambda^{n-1} \frac{(x - t)^{n-1}}{(n-1)!}$$

$$= 1 + \lambda(x - t) + \frac{(\lambda(x - t))^2}{2!} + \dots$$

$$= e^{\lambda(x - t)}$$

$$R(x, t; 1) = e^{x - t}$$

$$u(x) = f(x) + \lambda \int_0^x R(x,t;\lambda) f(t) dt$$

$$u(x) = x + \int_0^x e^{x-t} \cdot t dt = x + e^x \int_0^x t e^{-t} dt$$

$$u(x) = e^x - 1$$

$$e^u = 1 + u + \frac{u^2}{2!} + \frac{u^3}{3!} + \dots$$

$$\sin u = u - \frac{u^3}{3!} + \frac{u^5}{5!} - \dots$$

$$\cos u = 1 - \frac{u^2}{2!} + \frac{u^4}{4!} - \dots$$

$\forall u \in \mathbb{R}$

$$\frac{1}{1-u} = 1 + u + u^2 + u^3 + \dots \quad |u| < 1$$

Soln

$$K(x,t) = x - t$$

Volterra Mt. der Kernel
ist resolvent?

$$R(x,t;\lambda) = \frac{1}{\sqrt{\lambda}} \sinh [\sqrt{\lambda}(x-t)]$$

$$\sinh(u) = \frac{e^u - e^{-u}}{2} \quad \cosh(u) = \frac{e^u + e^{-u}}{2}$$

